

Thermo-dynamic plasma expansion acceleration in asymmetric spontaneous fast magnetic reconnection

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Asymmetric spontaneous fast magnetic reconnection model, in which the current sheet is initially put between two antiparallel straight magnetic field regions with different magnetic intensities, is studied by two-dimensional magnetohydrodynamic (MHD) simulations. Especially, the supersonic expansion acceleration process which has been already observed in the symmetric case is focused on. In this paper, we find that if the initial asymmetry features are weak and one side of the magnetic field regions consists of sufficiently low beta plasma, the supersonic expansion acceleration process is generated in the reconnection jet region, like the symmetric case. Hence, in such an asymmetric case, a fast shock is formed at the top of the magnetic loop.

1. Introduction

The spontaneous fast magnetic reconnection model proposed by Ugai and Tsuda (1977) describes a new type nonlinear instability that results from the positive feedback between macroscopic reconnection flows and microscopic anomalous resistivities. In this model, as the magnetic diffusion region is spontaneously localized by the nonlinear instability, slow shocks are generated, so that an active reconnection process is established. Then, as the reconnection process proceeds, a magnetic loop (plasmoid) is formed in the downstream of the fast plasma jet. In contrast to the Petschek model, the spontaneous fast magnetic reconnection model can have steady plasma jets exceeding the Alfvén velocity measured in the upstream field region of the reconnection layer. In fact, according to our two-dimensional magnetohydrodynamic (MHD) simulations, the final velocity of the plasma jet is observed to be superfast and reach 1.4 times of the Alfvén velocity, which is maintained until the jet encounters a fast shock generated in front of the plasmoid.

In recent studies, we found theoretically that the plasma acceleration is caused by the thermo-dynamic supersonic expansion acceleration mechanism (Shimizu and Ugai, 2000), which is caused, as follows. In the first step, the plasma is accelerated up to the Alfvén velocity measured in the upstream field region by one pair of slow shocks associated with the fast reconnection process. At the time, the Alfvén velocity in the upstream field region can exceed the local sound velocity in the downstream jet region, so that the plasma jet generated by slow shocks can be supersonic. In the second step, the supersonic plasma jet expands in the direction normal to the jet, associated with the swelling of the magnetic loop. The expansion of the plasma jet causes the thermo-dynamic supersonic plasma expansion acceleration, leading

to the plasma acceleration beyond the Alfvén velocity. Finally, the plasma jet terminates at a fast shock in front of the magnetic loop, leading to the enhancement of the swelling of the magnetic loop.

In this paper, we mainly study an asymmetric field case, in which two magnetic field regions separated by the current sheet have different field intensities and the same (uniform) plasma density. In Section 2, the simulation procedures are mentioned, and in Section 3, the results are shown. Sections 3 and 4 are devoted to the discussions and summary.

2. Procedures of MHD Simulation

A two-dimensional MHD simulation is executed in an initial asymmetric antiparallel magnetic field region, in which the initial magnetic field intensity B_{x2} in the lower side magnetic field region is higher than B_{x1} in the upper side magnetic field region, as shown in Fig. 1. In this paper, the value B_{x2} is taken to be 1.5 (or 1.0 for the symmetric case), and B_{x1} is fixed to be 1.0. The plasma density is initially uniform ($\rho_0 = 1$). The initial pressure P_0 is determined by the pressure balance equation $P_0 + B_{x0}^2 = C$; C is constant in space and given by $P_2 + B_{x2}^2$ (P_2 is the initial pressure in the lower side magnetic field region and set to be 0.1). The so-called symmetry boundary condition, which works as a wall boundary condition, is embedded in the left side, upper and lower boundary lines in Fig. 1. Free (open) boundary condition is embedded in the right side boundary line.

The details of the simulation procedures are mentioned in our previous papers (Ugai and Shimizu, 1996; Shimizu and Ugai, 2000). The normalization is as follows. The distances $\vec{r} = (x, y)$ are normalized by d_0 , which is the half width of the initial current sheet. The magnetic field \vec{B} is by B_{x1} in the upper field region, pressure P is by B_{x1}^2/μ_0 , density ρ is by ρ_0 , current J_z is by $B_{x1}/\mu_0 d_0$, plasma velocity \vec{u} is by $V_{A1} = B_{x1}/\sqrt{\mu_0 \rho_0}$ and time is by d_0/V_{A1} . The anomalous resistivity is assumed to be $\eta = k_R[V_D(\vec{r}, t) - V_C]$ for $V_D > V_C$ and $\eta = 0$ for $V_D < V_C$, and assumed to be isotropic.

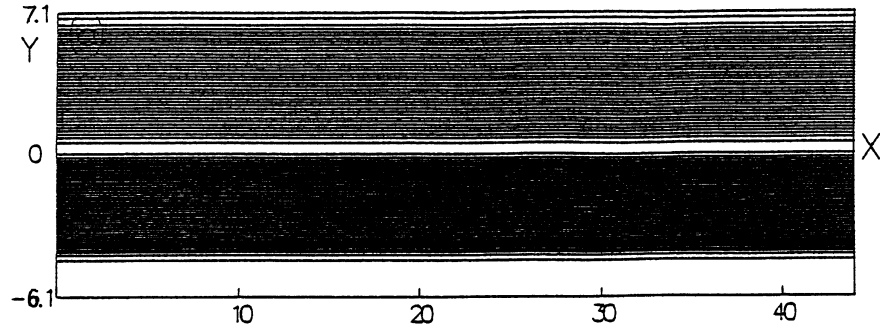


Fig. 1. Initial magnetic field. The upper and lower regions have $B_{x1} = 1.0$, and $B_{x2} = 1.5$, respectively.

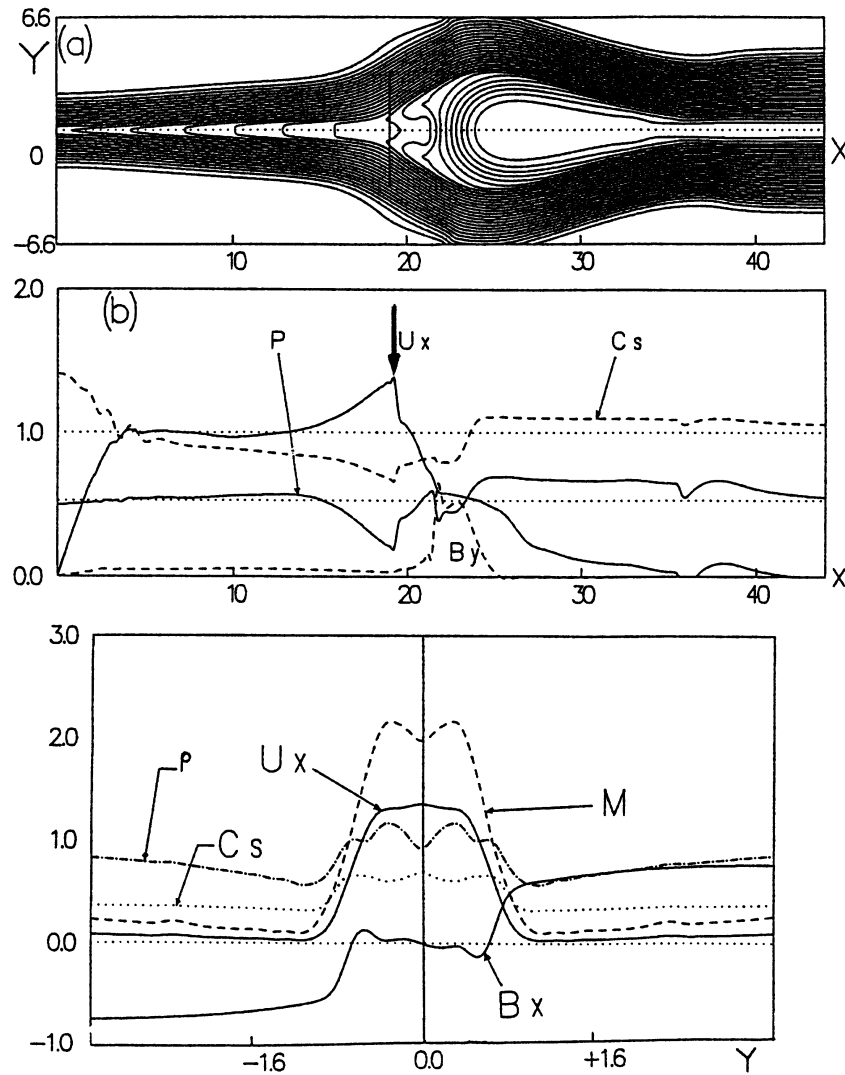


Fig. 2. Symmetric case. (a) Magnetic field at the time when the reconnection process has been fully developed. (b) The profiles of the pressure P , velocity U_x , magnetic field B_y and local sound velocity C_s along the x -axis. A downward thick arrow indicates the position of the fast shock. (c) The profiles of ρ , C_s , B_x , U_x and $M = U_x/C_s$ along the y -directional line at $x = 19.0$, which is including the max velocity U_x point.

The value V_D is given by $|\vec{J}/\rho|$, $k_R = 0.002$ and $V_C = 4.0$. The anomalous resistivity is normalized by $\mu_0 d_0 V_{A1}$. The simulation box is taken to be $L_x = 44.0$ and $L_y = 13.2$.

Then, the outline of the simulation is as follows. In time $0 < t < 4$, the magnetic field configuration around the

origin is destabilized by the small resistive disturbance. After the resistive disturbance is removed at time $t = 4$, an X-type field configuration formed locally at the origin causes the current sheet thinning, due to the resulting weak plasma flows. The thinning of the current sheet eventually enhances

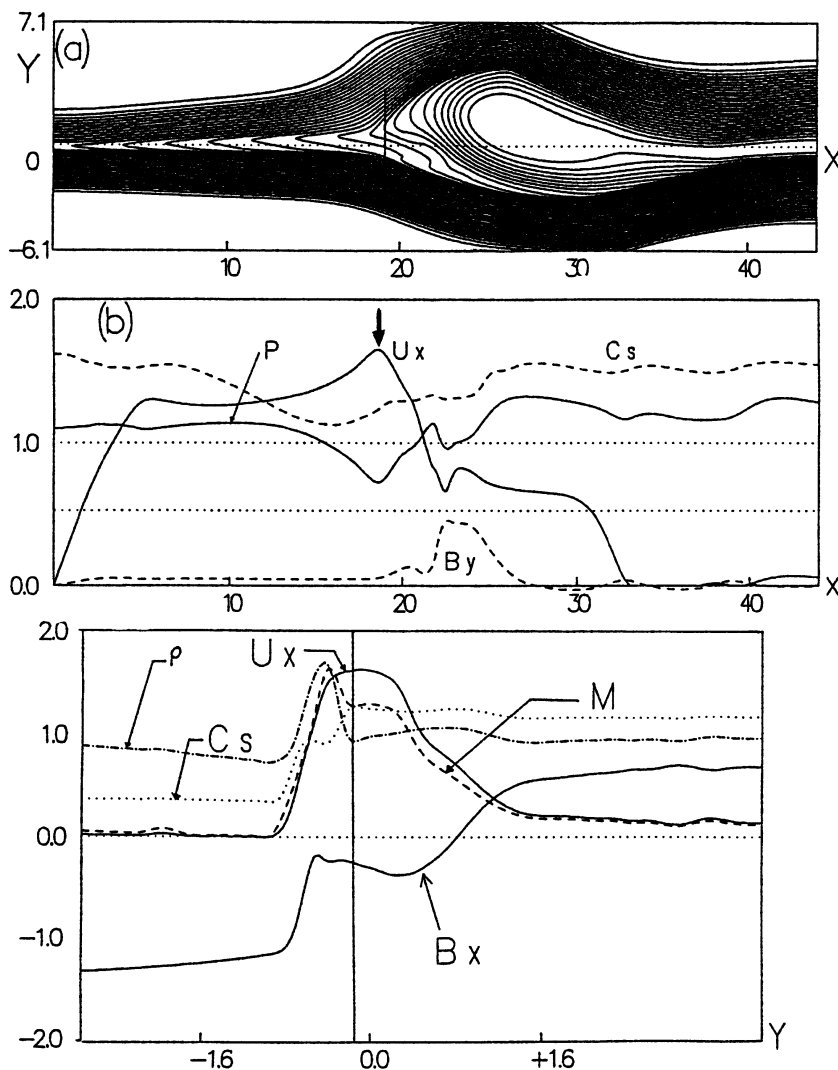


Fig. 3. Asymmetric case ($B_{x1} = 1.0$, and $B_{x2} = 1.5$). In (b), the profiles are obtained along a horizontal line ($y = 0.17$) including the max velocity point. The other caption is similar to Fig. 2. (c) This is also similar to that of Fig. 2. But, it is plotted along a y -directional line ($x = 18.6$).

the current-driven anomalous resistivity around the origin. Since the anomalous resistivity and magnetic reconnection flow simultaneously grow to enhance each other, the fast magnetic reconnection mechanism is spontaneously built up ($t > 30$).

3. Simulation Results

3.1 Symmetric case

Figure 2 is obtained in the symmetric case ($B_{x1} = B_{x2} = 1.0$). Figures 2(a) and (b) respectively show the magnetic field and profiles of the pressure P , plasma jet's velocity U_x , y -directional field component B_y , and local sound velocity C_s along the x -axis at the time when the fast reconnection has been fully developed. In Fig. 2(a), a growing magnetic loop associated with the reconnection process is running in the positive x direction. The diffusion region is strongly localized around the origin ($x < 3$) and the region size is much smaller than the simulation box ($0 < x < 44$), so that the Petschek reconnection model is well established in $0 < x < 13$ in Figs. 2(a) and (b). In fact, U_x in $4 < x < 13$ almost coincides with the Alfvén velocity $V_{A1} = V_{A2} = 1.0$

measured in the initial upstream field region. By the way, the region of $4 < x < 13$ is supersonic, because of $U_x > C_s$. Considering that the local sound velocity C_s is almost equal to the local fast wave velocity in the high beta plasma jet, it means that the plasma jet generated by slow shocks can be superfast. However, in $13 < x < 19$, we can easily find a region in which U_x largely exceeds the Alfvén velocity. Since the field intensity and Alfvén velocity in the upstream field region gradually decreases, as the reconnection proceeds, such a high-speed plasma jet cannot be explained by the slow shock acceleration associated with the fast reconnection process. Instead, it was found that the supersonic expansion acceleration mechanism causes the acceleration, as mentioned in the introduction. Since this simulation is started from the symmetric magnetic field, everything proceeds symmetrically around the x -axis. Figure 2(c) shows the profiles of the plasma density ρ , B_x , U_x and Mach number $M = U_x/C_s$ along the y -directional line at $x = 19.0$. As shown in Fig. 2(c), the superfast jet region ($M > 1$) symmetrically spreads in the whole of the reconnection jet located between two slow shocks ($y = 0.8$ and -0.8). These slow

shocks are respectively combined with the transient intermediate waves (Ugai and Shimizu, 1994).

3.2 Asymmetric case

Figure 3 shows the result obtained in an asymmetric case for $B_{x1} = 1.0$ and $B_{x2} = 1.5$. Figures 3(a), (b) and (c) show the magnetic field and profiles similar to those of Figs. 2(b) and (c), respectively. Note that the profiles in Fig. 3(b) and (c) are respectively plotted along the horizontal line ($y = 0.17$) and vertical line ($x = 18.6$) which include the point of the fastest jet velocity U_x in the entire simulation region. The generated magnetic loop is distorted, due to the asymmetric initial field configuration. Especially, the magnetic loop is largely swelling toward the upper side field region, which has a weaker field intensity than the lower side field region. Also in this case, a superfast jet region ($U_x > C_s$) can be seen in Figs. 3(b) and (c). However, in Fig. 3(b), the superfast (supersonic) region seems to be narrower than the symmetric case (Fig. 2(b)). In addition, Fig. 3(c) shows that the maximum of the Mach number ($= 1.7$) is lower than that ($= 2.2$) of the symmetric case, and the peak of the Mach number shifts to the side of the high intensity field region (left side; $y < 0$). Note that the U_x in Fig. 3(c) is almost uniform in the jet region (roughly, $-0.5 < y < 0.5$). It suggests that the reconnection jet almost reaches a steady state.

4. Discussions

4.1 Generation of the superfast jet

Basically, the supersonic expansion acceleration mechanism requires that the reconnection jet generated by slow shocks is superfast. Now, the Alfvén velocities in the upper and lower side magnetic field regions are initially $V_{A1} = B_{x1}/\sqrt{\rho_1}$ and $V_{A2} = B_{x2}/\sqrt{\rho_2}$, respectively. The Alfvén velocity may be considered to be the maximum jet velocity generated by the slow shock, which is just a switch off shock. In the symmetric case, in fact, the reconnection jet's velocity becomes close to the Alfvén velocity ($V_{A1} = V_{A2}$), as shown in Fig. 2(b). But, in the asymmetric case started from the uniform plasma density assumed here, the slow shock is always weaker than the switch off shock. In addition, even in a steady state of the asymmetric reconnection jet, the velocity U_x is almost uniform in the whole of the jet region, as shown in Fig. 3(c). It suggests that the plasma acceleration by the lower side strong slow shock ($y < 0$) is prevented by the slow jet generated by the upper side weak slow shock ($0 < y$), and finally, the reconnection jet velocity must have a constant velocity less than V_{A2} . On the other hand, because of the uniform density and pressure balance $P + B^2 = \text{const.}$ assumed initially, the sound velocity $C_s = \sqrt{P/\rho}$ in the upper side field region ($0 < y$) is higher than that of the lower side field region ($y < 0$). Accordingly, also in the reconnection jet region, the sound velocity in the upper side of the jet tends to be higher than the sound velocity in the lower side.

Hence, because of the uniform jet velocity and non-uni-

form sound velocity in the upper and lower side of the jet region, the upper side region of the reconnection jet tends to have lower Mach number than the lower side of the jet region. As a result, as shown in Fig. 3(c), the higher Mach number jet region tends to shift to the lower side jet region in which the plasma is supplied from the strong intensity field region ($y < 0$).

4.2 Expansion of the superfast jet

The swelling of the magnetic loop (plasmoid) causes the expansion of the plasma jet in the direction normal to the jet, due to the magnetic field tension. Since the swelling is intrinsically caused by the break of the initial pressure balance between the magnetic loop and surrounding magnetic field region in the fast reconnection process, the expansion of the reconnection jet should always occur in front of the magnetic loop. Hence, once the supersonic jet is generated by slow shocks, the supersonic jet is accelerated by the supersonic expansion acceleration mechanism.

5. Summary

Asymmetric spontaneous fast reconnection process was studied in MHD simulation of initial uniform plasma density. We found that when one of the two antiparallel magnetic field regions separated by the current sheet is filled with sufficiently low beta plasma and the two field intensities B_{x1} and B_{x2} is close (asymmetric effect is weak), the supersonic adiabatic expansion acceleration process can be caused, like the symmetric case. However, the obtained result suggests that as the field intensities in the upper and lower magnetic field regions are largely different, the acceleration becomes weaker and may finally not work. In the next step, the supersonic expansion acceleration process must be theoretically studied in various asymmetric cases which have various plasma conditions. It may be partially related to the general works for asymmetric reconnection models done by Semenov *et al.* (1983).

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