

# Estimation of the source model for the foreshock of the 2004 off the Kii peninsula earthquakes and strong ground motion simulation of the hypothetical Tonankai earthquake using the empirical Green's function method

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We estimated the source model for the foreshock of the 2004 off the Kii peninsula earthquakes by empirical Green's function modeling. The size and the rise time of the strong motion generation area (SMGA) were estimated to be  $30 \times 15$  km, and 0.9 sec, respectively. The stress drop of the SMGA was calculated to be 8.3 MPa. This model could reproduce long-period ground motions following the direct *S*-wave observed in the Osaka basin well. Using the derived source parameters, we simulated strong motions of the hypothetical Tonankai earthquake. Distribution of the seismic intensity derived here is similar to that obtained by the previous report. We could predict long-period ground motions which last for a long duration at the basin sites.

**Key words:** Empirical Green's function method, foreshock of the 2004 off the Kii peninsula earthquakes, source model, stress drop, strong ground-motion simulation, hypothetical Tonankai earthquake.

## 1. Introduction

At 19:07 on 5 September 2004, an  $M_{JMA}7.1$  (magnitude determined by Japan Meteorological Agency, JMA) earthquake occurred in the south east off the Kii peninsula, Japan. About five hours later, a larger  $M_{JMA}7.4$  earthquake took place about 30 km away from the first one. We call the latter large event the mainshock of the 2004 off the Kii peninsula earthquakes and take the 19:07 one as its foreshock. These earthquakes and their aftershocks are thought to be intraplate earthquakes, which occurred in the subducting Philippine Sea Plate (The Headquarters for Earthquake Research Promotion, hereafter HERP, 2004). In order to examine the source characteristics of these earthquakes, we estimated the source model for the foreshock comparing the observed and synthetic strong-motion waveforms. The reason why we would like to model not the mainshock but the foreshock, is that the latter rupture seems to be simpler than the former (e.g. Yagi, 2004; Yamanaka, 2004).

Because the wave observed on land passed through the long propagation path and was affected by the complex underground structure, it might be difficult for a theoretical approach to reproduce the strong motion records. So we used the empirical Green's function (EGF) method, which originated with Hartzell (1978) to calculate a record of an earthquake by summing up that of a smaller event located near the larger one. Using the EGF method developed by Irikura

(1986), the observed broadband strong-motion records can be simulated well on the assumption of a characterized simple fault model, which is a rectangle in shape with a constant slip and stress drop (e.g. Kamae and Irikura, 1998; Kamae and Kawabe, 2004; Miyake *et al.*, 2003). Miyake *et al.* (2003) called this area the strong motion generation area (SMGA). They showed that in most cases, the SMGA corresponds to the asperity area which is observed in the slip distribution inverted using relatively low frequency ( $<1$  Hz) strong motion records. We took the same approach as the studies above to model the seismic source.

Near the epicenters of the 2004 off the Kii peninsula earthquakes, a large subduction zone earthquake called the Tonankai earthquake has repeated itself throughout history. The next Tonankai earthquake is expected to occur with a high probability in the near future (HERP, 2001a). The 2004 off the Kii peninsula earthquakes would provide valuable information to grasp the gross characteristics of the strong motion of the Tonankai earthquake, especially its propagation effect, although their source regions were not exactly the same. Using the estimated source parameters for the foreshock analysis, we also carried out an EGF simulation of the ground motion caused by the hypothetical Tonankai earthquake which showed some characteristics of the simulated strong ground motions.

## 2. Estimation of the Source Model of the Foreshock

### 2.1 Data and analysis

We used strong-motion records obtained by F-net. Their stations can be supposed as rock sites. Because the records are less contaminated by site effects, they are thought to be better for observing the source characteristics. Figure 1

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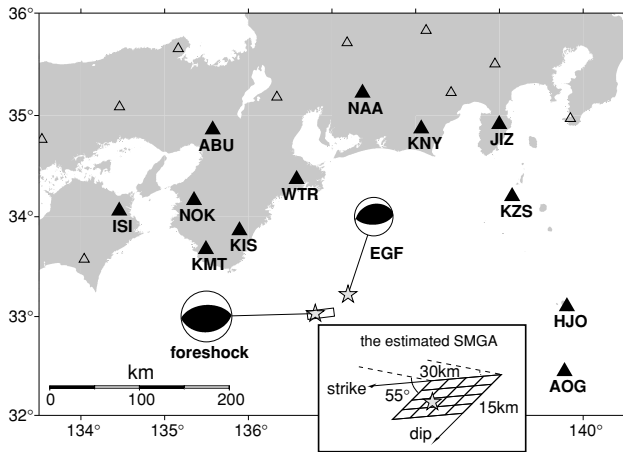


Fig. 1. Distribution of the F-net stations used for the estimation of the source model of the foreshock (closed triangle). Geometry of the estimated SMGA of the foreshock is also shown.

shows the stations we used for this study.

We used the records of the  $M_{JMA}5.5$  aftershock at 3:36 on 8 September as the EGF. Source parameters of the foreshock and the EGF aftershock are listed in Table 1. We calculated the synthetic waveforms according to the EGF method proposed by Irikura (1986). Irikura's method is based on the  $\omega^{-2}$  source scaling relation between the large and small earthquakes. To obey this scaling, the number to divide the SMGA into subfaults ( $N \times N$ ) and the ratio of the stress drop of the large earthquake to the small one ( $C$ ) are determined from the spectral ratio of the two events (Miyake *et al.*, 2003). Reading the flat levels of the high and low frequencies,  $N$  and  $C$  were determined as 4 and 2.5, respectively. The focal mechanism of the EGF event resembled that of the foreshock as seen in Fig. 1. A plane dipping to the north was chosen as the fault plane from a pair of nodal planes of the moment tensor solution determined by the F-net, referring to Yagi (2004) and Satake *et al.* (2005). Rupture was assumed to propagate radially from the hypocenter determined by JMA, which was located in the SMGA.

We searched the size of the SMGA, the rupture propagation direction, and the rise time, using the genetic algorithm (GA). The searching ranges of the length of the SMGA and the rise time were 0.4–60.0 km and 0.04–5.0 sec and the width was assumed to be half of the length. The rupture velocity was fixed in each GA search. We tried four cases where the rupture velocity was 1.8, 2.2, 2.6, and 3.0 km/s. As the evaluation function for the GA search, we used the sum of the residual value of horizontal velocity waveforms and acceleration envelopes for 30 sec from 2 sec before the  $S$ -wave's arrivals. The frequency band for velocity was set to be 0.05–2.0 Hz, while that for acceleration was 0.05–20.0 Hz. We did the GA search with 100 initial models and obtained an improved model after 100 generations. We performed this procedure five times, changing the sets of initial models each time.

## 2.2 Result

When the rupture velocity was 3.0 km/s, the five searches gave similar results listed in Table 2 and smaller residual

value. From this result, we estimated the length and the width of the SMGA, and the rise time to be 30 km, 15 km, 0.9 sec, respectively. The rupture started at the subfault which was third along the strike and third along the dip direction (Fig. 1). This means that the rupture directivity effect was not very strong. Figure 2 shows an example of the comparison between the observed and synthetic waveforms. The fitting of acceleration and velocity waveforms is fairly good. As the stress drop of the EGF event was 3.3 MPa from the formula of Eshelby (1957) with the area 28.1 km<sup>2</sup> and the seismic moment  $2.06 \times 10^{17}$  Nm, the stress drop on the SMGA of the foreshock was calculated to be 8.3 MPa.

## 2.3 Discussion

The sequence of the 2004 off the Kii peninsula earthquakes is thought to have taken place in the subducting plate. Asano *et al.* (2003) indicated that intraslab earthquakes have larger stress drops on the SMGA than crustal earthquakes. They also observed the larger stress drop on the SMGA for the deeper events. The stress drop we estimated here is similar to that of crustal earthquakes. We used the hypocenters determined by JMA. Aftershock depths obtained using ocean bottom seismometer data were reported to be much shallower than those determined by JMA (HERP, 2004). Ito *et al.* (2005) also obtained a shallow centroid depth for these earthquakes. The relatively smaller stress drop for an intraslab earthquake obtained here may be due to the shallower focal depth. Since a change of the focal depth makes little difference of the hypocentral distance, it scarcely affects our estimation of the SMGA size.

We simulated the records of the stations located in the Osaka basin maintained by the Committee of Earthquake Observation and Research in the Kansai Area (CEORKA) from the estimated source model. Our purpose is to examine whether the long-period ground motion observed in the basin site can be reproduced from an EGF that might have smaller power over longer periods. A velocity-type strong-motion seismograph has been installed at the CEORKA stations, which provides higher quality data for long periods. Figure 3 shows the comparison between the observed and synthetic velocity waveforms and those spectra. Later phases with long duration can be reproduced well. We can conclude that records of the EGF event have a large enough S/N ratio to reproduce the long-period ground motion in the Osaka basin.

## 3. Strong Motion Simulation of the Hypothetical Tonankai Earthquake

### 3.1 Data and analysis

In the previous section, the source size and the stress drop of the EGF event for the foreshock was determined as 28.1 km<sup>2</sup> and 3.3 MPa. Using this event as the EGF again, we anticipated the hypothetical Tonankai earthquake and simulated the resultant strong ground motions. Although the type of earthquake was different, the focal mechanism of the EGF event acceptably resembled that of the hypothetical Tonankai earthquake. We followed Model 2 used in HERP (2001b). This model consists of three asperities and gives a larger stress drop on the smaller asperities, as shown in Fig. 4. We only characterized the asperity por-

Table 1. Information of the foreshock of the 2004 off the Kii peninsula earthquakes and the aftershock used as EGF. Superscript 1 denotes the parameter estimated by JMA and 2 that estimated by F-net.

	Foreshock	EGF
Date	2004/09/05 19:07	2004/09/08 03:36
Latitude <sup>1</sup>	33.03°N	32.96°N
Longitude <sup>1</sup>	136.80°E	137.32°E
Depth <sup>1</sup>	37.6 km	39.7 km
M <sub>JMA</sub>	7.1	5.5
Strike <sup>2</sup>	263°; 92°	254°; 92°
Dip <sup>2</sup>	55°; 36°	34°; 57°
Rake <sup>2</sup>	85°; 97°	75°; 100°
Seismic moment <sup>2</sup>	$7.73 \times 10^{19}$ Nm	$2.06 \times 10^{17}$ Nm

Table 2. Source parameters of the foreshock obtained by the GA search for five trials.

	Trial 1	Trial 2	Trial 3	Trial 4	Trial 5
Length of the SMGA	30.496 km	30.556 km	30.676 km	30.496 km	30.440 km
Width of the SMGA	15.248 km	15.278 km	15.338 km	15.248 km	15.220 km
Rise time	0.870 sec	0.888 sec	0.908 sec	0.880 sec	0.868 sec
Rupture starting subfault	(3,3)	(3,3)	(3,3)	(3,3)	(3,3)

Table 3. Source parameters modeled for the hypothetical Tonankai earthquake. Location of the each asperity is seen in Fig. 2. Parenthetic values in the column of depth of the rupture starting point is the rupture starting time measured from the time when the first asperity starts to break.

	Strike	Dip	Depth of the rupture starting point	Size	Seismic moment	Stress drop
Asperity 1	210°	15°	23.1 km (0.0 sec)	702 km <sup>2</sup>	$1.40 \times 10^{20}$ Nm	21.9 MPa
Asperity 2	230°	15°	20.4 km (26.6 sec)	1376 km <sup>2</sup>	$3.75 \times 10^{20}$ Nm	20.1 MPa
Asperity 3	270°	15°	23.1 km (51.7 sec)	702 km <sup>2</sup>	$1.40 \times 10^{20}$ Nm	21.9 MPa

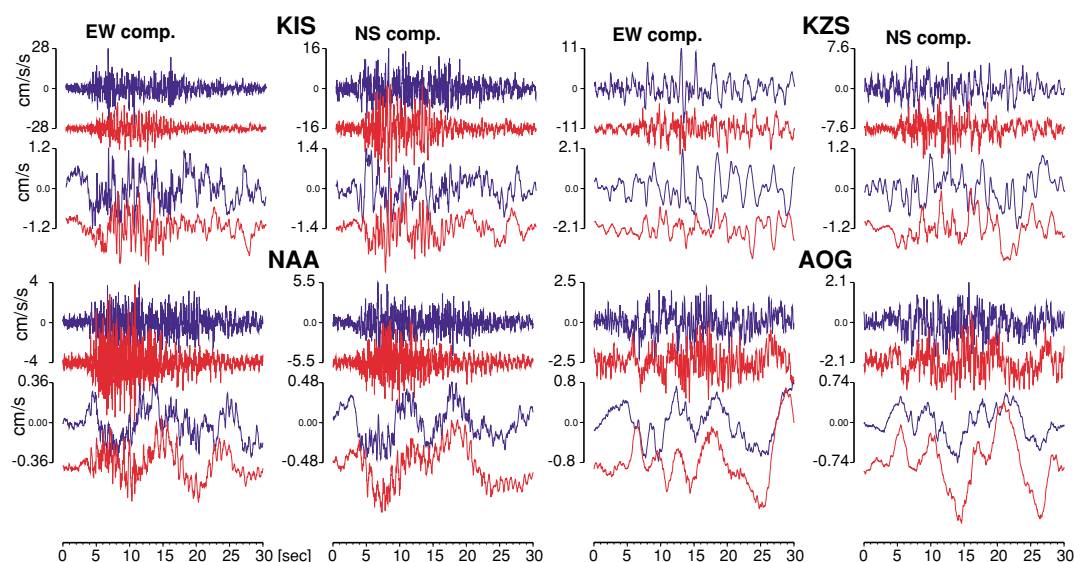


Fig. 2. Example of the fitting between observed (blue) and synthetic (red) waveforms at the four F-net stations. The upper pair for each station shows the acceleration waveforms, and the lower pair shows the velocity. Both waveforms are band-pass filtered for 0.05–20.0 Hz.

tion, and ignored the background off-asperity area. The source parameters for each asperity are listed in Table 3.  $N$  and  $C$  of each asperity were determined in order to fit the size and the stress drop of the asperities with those used in

HERP (2001b). The rupture starts from off the Kii peninsula and propagates in a north-easterly direction. We calculated the acceleration, velocity, and displacement waveforms predicted at the stations K-NET, KiK-net, and CE-

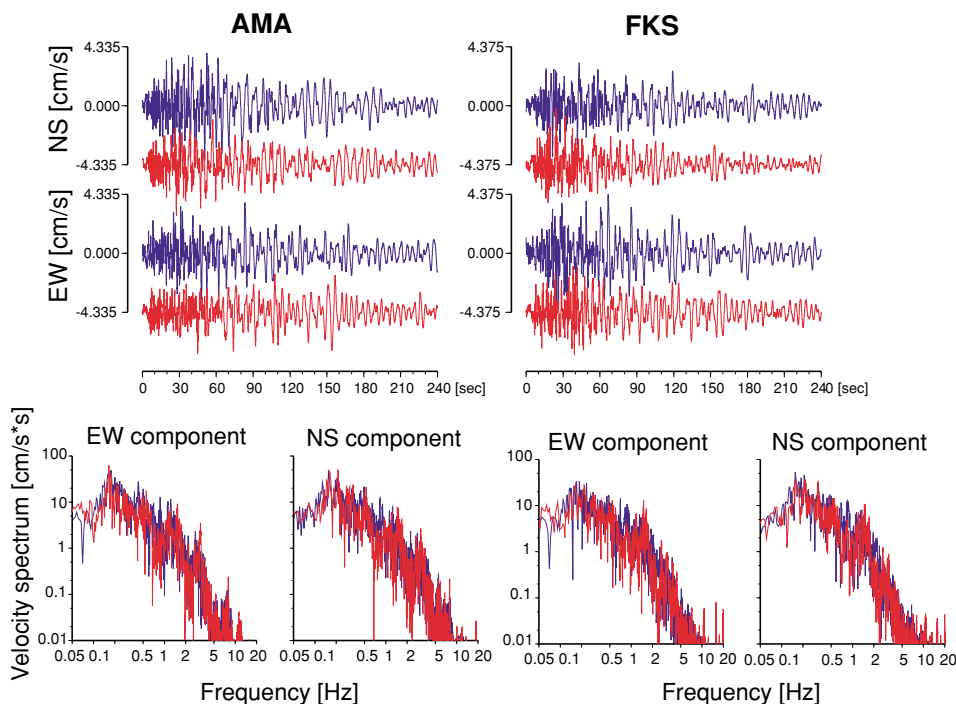


Fig. 3. Comparison between velocity waveforms observed at stations in the Osaka basin and that simulated assuming the obtained source model (upper) and comparison of the velocity spectra (lower). Blue lines are the observations and the red lines are the simulations.

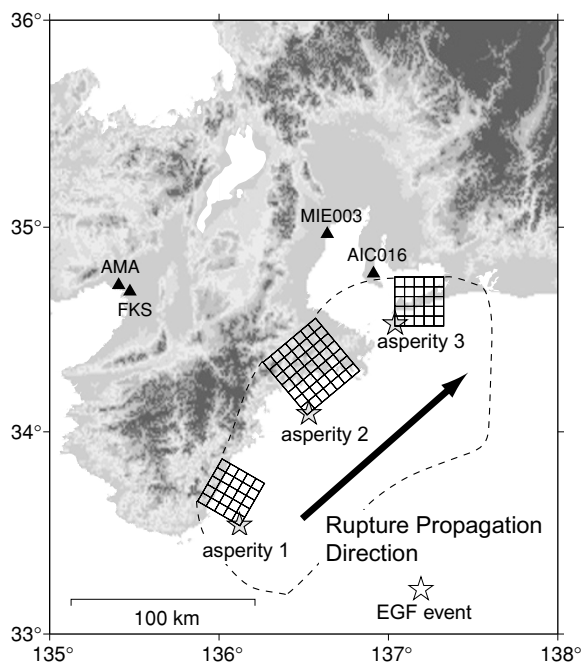


Fig. 4. Source model of the hypothetical Tonankai earthquake used in this study. Each star indicates the rupture starting point of each asperity.

ORKA, where the records of the EGF event were available. The frequency band used for this simulation was 0.05–20.0 Hz. The rupture velocity was assumed to be 2.7 km/s, referring to HERP (2001b).

**3.2 Result**

The peak horizontal velocity (PHV) of synthetic data is compared with the empirical attenuation relation proposed

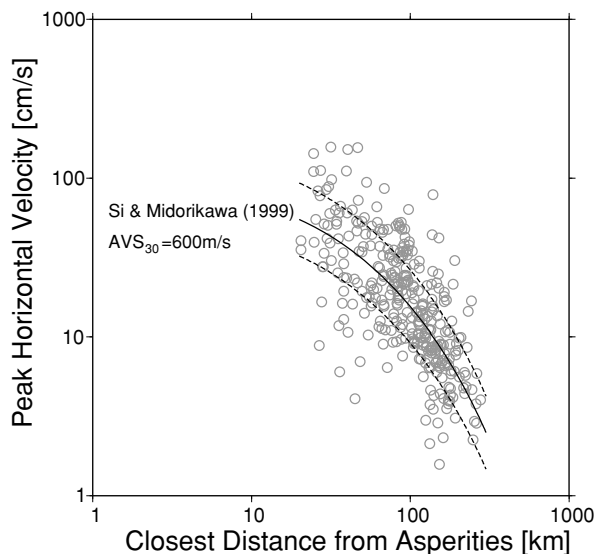


Fig. 5. Relationship of peak horizontal velocity to the closest distance from the asperity. The solid line is the empirical attenuation curve for the site where  $V_s$  is 600 m/s derived by Si and Midorikawa (1999). Broken lines indicate its standard deviation.

by Si and Midorikawa (1999) in Fig. 5. Our simulation was performed by a linear summation. Although the empirical relation was derived from compiling the data corrected for site amplification, we did not make any correction to the predicted PHV. This may cause some scattering of the predicted PHV from the empirical relation. Nevertheless, the predicted PHV follows the empirical attenuation relation to a large extent.

Figure 6 shows the distribution of seismic intensity (JMA, 1996) calculated from simulated acceleration wave-

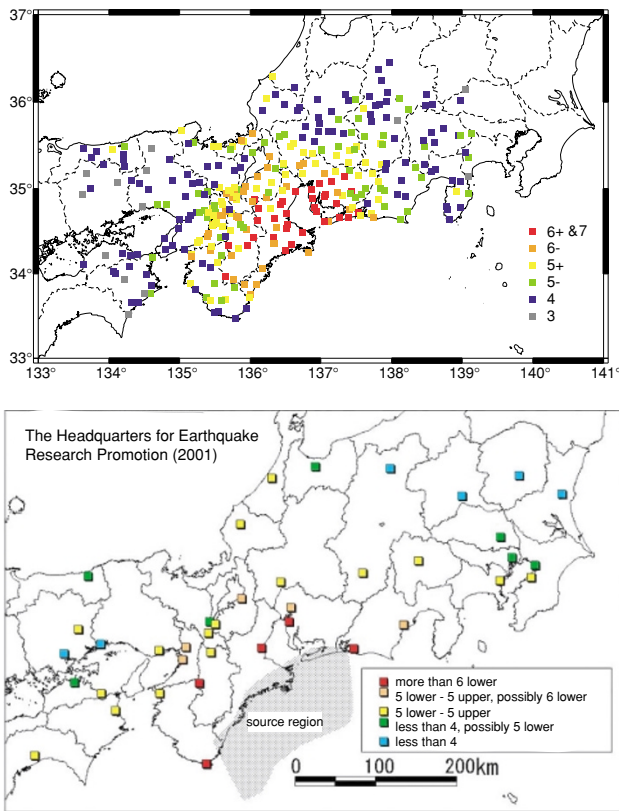


Fig. 6. Distribution of the seismic intensity calculated by this study (upper) and that calculated by the Headquarters for Earthquake Research Promotion (2001b, lower).

forms. This is generally consistent with that calculated by HERP (2001b), which used the stochastic Green's function method. Large seismic intensities of more than 5+ were predicted for the Aichi and Mie prefectures, which is located toward the rupture propagation.

Examples of the velocity waveforms for the stations in the Aichi and Mie prefectures (AIC016 and MIE003) and the Osaka basin (FKS and AMA) are shown in Fig. 7. At the stations in the Osaka basin, long-period ground motions last for more than 3 min. At MIE003, long-duration ground motions are also observed after the direct *S*-wave. On the other hand, the waveform predicted at AIC016 mainly contains a high frequency component with very large amplitude. Seismic intensity 7 was predicted for this station. The depth to the bedrock at MIE003 is deeper than that at AIC016, although both stations are located in the Nobi basin.

### 3.3 Discussion

The frequency band we mainly aimed at in this simulation was associated with the low frequency ground motion observed in the basin site (around 0.2 Hz) and the seismic intensity (up to several Hz). Kamae and Kawabe (2004) succeeded in simulating the ground motion of the 2003 Tokachi-oki earthquake ( $M_{JMA} 8.0$ ), whose frequency band was between 0.1 and 10.0 Hz, using a source model that consisted only of asperities. We then considered that we could obtain a satisfactory result to the frequency band in which we were interested by characterizing only the asperities from the source model of HERP (2001b). Such a model gave a similar distribution of seismic intensity to that calculated by HERP (2001b) and the PHV attenuation relation which was consistent with the empirical relation for many

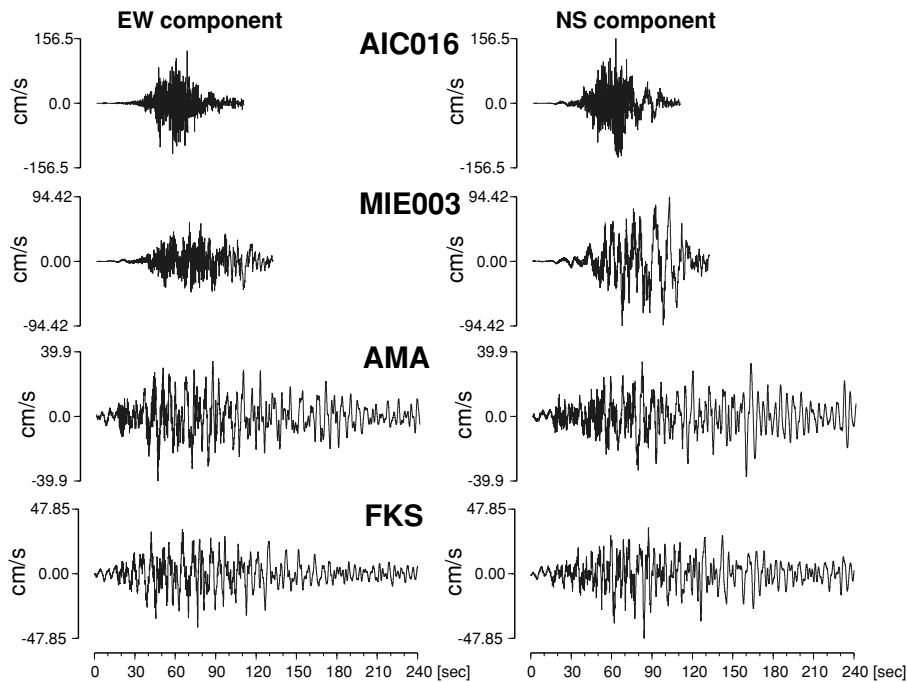


Fig. 7. Example of horizontal velocity waveforms predicted for the stations in the Aichi and Mie prefectures (AIC016 and MIE003) and in the Osaka basin (AMA and FKS).

stations. This is probably because the asperity is a major contributor to the waves with the frequency band analyzed in this study. Since the EGF event had enough power, even for low frequency as mentioned in the discussion section of the foreshock analysis, low-frequency ground motion in the Osaka basin could be simulated. Our simulation provides the main characteristics of the strong ground motions of the hypothetical Tonankai earthquake. Of course, the background area should be considered for a more thorough simulation. It would be necessary to examine how to set the source parameters for the background area and carry out a simulation using a source model that consist of both asperity and background region.

#### 4. Conclusion

We estimated the source model to explain the broadband waveform of the foreshock of the 2004 off the Kii peninsula earthquakes by the empirical Green's function method. After five trials of the GA search, we estimated that the size of the SMGA is  $30 \times 15$  km, on the assumption that the aspect ratio is 2:1. The stress drop in the SMGA was calculated to be 8.3 MPa, which is comparable to that of crustal earthquakes. Using the same EGF as the foreshock analysis, we made a strong motion simulation of the hypothetical Tonankai earthquake. In both analyses, the long period ground motion in the Osaka basin could be produced, even when using a relatively small earthquake as the EGF.

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