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Spatio-temporal distribution of shallow very-low-frequency earthquakes between December 2020 and January 2021 in Kumano-nada, Nankai subduction zone, detected by a permanent seafloor seismic network

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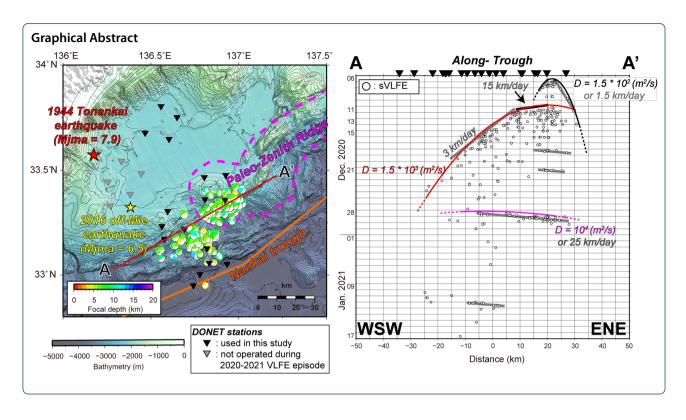
Abstract

We estimate the hypocenter locations and the centroid moment tensor solutions of the shallow very-low-frequency earthquake (sVLFE) activity that occurred in the Kumano-nada region of the Nankai Trough megathrust zone in central Japan from December 2020 to January 2021. Using seafloor observation data, we examined the detailed spatiotemporal distribution of the sVLFE activity. During this episode, the activity area was within the vicinity in which the sVLFE activity has been observed in the past and can be divided into two major parts. The sVLFE activity started from the eastern side and remained there for the first 5 days and then migrated to the western side via secondary expansion. The eastern active area is located just below the outer ridge and coincides with the location where the paleo-Zenith Ridge subducted. The western activity area is centered between the outer wedge and the outer ridge with the primary active area being at the outer wedge. Comparing the activity in the eastern and western areas, the eastern side is more active, but the individual moment releases on this side are smaller than those on the western side. This may indicate a difference in the fluid pressure along the plate boundary between the eastern and western areas. After the second expansion of the active area, we observed several migration patterns within the expanded area with a faster velocity than those of the initial and second expansions. The direction of these migrations is opposite to that of the first and second expansions. This indicates that the fluid pressure and/or stress level in the sVLFE generation region changed with time within this episode. Furthermore, many waveforms with sVLFE characteristics were observed at only one or a few observation points near the trough axis in the middle to latter half of January 2021. This indicates the occurrence of small-scale sVLFEs in the vicinity of the trough axis at the end of this sVLFE episode.

Keywords: Nankai Trough, Shallow very-low-frequency earthquake, Centroid moment tensor (CMT) solution, Slow earthquake, Dense Oceanfloor Network System for Earthquakes and Tsunamis (DONET)

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Introduction

The Nankai Trough located in central Japan is a wellknown megathrust zone where M~8 class earthquakes have repeatedly occurred with intervals of 100–200 years, including the 1944 Tonankai earthquake (Mw=7.9) (e.g., Ando 1975) (Fig. 1a). The Philippine Sea Plate is subducting beneath the Amur Plate with an average relative velocity of 6 cm year⁻¹ (Argus et al. 2011). Geodetic observation data show that several zones of strong coupling between the overriding and subducting plates exist in the Nankai forearc (Nishimura et al. 2018; Yokota et al. 2016). Adjusted areas of these strong coupling zone are well correlated with the source area of slow earthquakes, whose activities indicate that the intraplate coupling changes with time (Obara and Kato 2016; Behr and Bürgmann 2021). Therefore, the intensive monitoring of slow earthquakes is important to understand the nature of the seismogenic zone, which may also help mitigate future disasters.

Most slow earthquakes occur in the transition zone of the intraplate coupling where the seismogenic strong coupling takes on a rheological creeping nature. In the Nankai Trough, slow earthquakes are detected on both the up-dip and down-dip sides of the subduction zones (e.g., Obara and Kato 2016). The activities on the down-dip side have been well studied using dense seismic and geodetic observation networks in the Japanese Islands. For example, Shelly et al. (2006) found that low-frequency

earthquakes occurred along the plate boundary, whereas ordinary earthquakes occurred within the subducted oceanic crust. Recent studies on the detailed spatiotemporal distribution of deep tectonic tremors demonstrate that slow-slip transients contain a multitude of smaller, temporally clustered fault slips whose migration is controlled by a diffusional process (Kato and Nakagawa 2020). Conversely, land observations provide a limited ability to study slow earthquakes on the up-dip side. Even though Takemura et al. (2019a, b) determined a centroid moment tensor (CMT) for shallow very-low-frequency earthquakes (sVLFEs), they assumed that all sVLFEs occurred along the plate boundary fault. As these events occur outside the network, their estimated locations have large errors in the depth and along-dip directions. It is necessary to investigate in detail the sVLFE locations without assuming a focal depth and to discuss the relationship between their depths and the plate boundary.

Offshore observations are crucial for detailed studies of slow earthquakes on the up-dip side. Observations using self-pop-up-type ocean bottom seismometers (OBSs) detected low-frequency tremors and earthquakes in Kumano-nada (Obana and Kodaira 2009; Tamaribuchi et al. 2019) and Hyuga-nada (Yamashita et al. 2015). Using broadband OBSs, Sugioka et al. (2012) detected sVLFEs that occurred along the plate boundary fault. The Dense Oceanfloor Network System for Earthquakes and Tsunamis (DONET; gray diamonds in Fig. 1; Kaneda

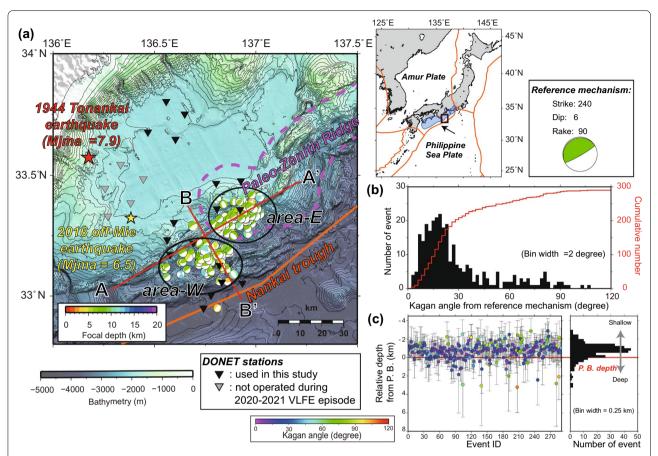


Fig. 1 Study area and observed shallow very-low-frequency earthquake (sVLFE) distribution. **a** Distribution of the centroid moment tensor (CMT) solutions of the sVLFEs and the Dense Oceanfloor Network System for Earthquakes and Tsunamis (DONET) stations on a bathymetry map. The color of the CMT solutions indicates the focal depth. The area outlined by the pink dashed line indicates the location where the paleo-Zenith Ridge subducted (Park et al. 2004). The epicenters of the 1944 Tonankai and 2016 off-Mie earthquakes are indicated by red and yellow stars, respectively. The right-top panel shows the regional map and the surrounding plate boundaries (Bird 2003). The dark brown rectangle indicates the area shown in **a**. Blue-masked areas correspond to the assumed areas of the Tokai, Tonankai, and Nankai seismogenic zones. The arrow shows the relative motion vector of the Philippine Sea Plate to the Amur Plate (Argus et al. 2011). **b** Distribution of the Kagan angle of the CMT solutions with respect to the reference mechanism assuming a pure thrust fault along the plate boundary. **c** Relationship between the average focal depth estimated using the bootstrap method and the plate boundary model (Nakanishi et al. 2018). The color and the vertical bar in the left panel indicate the Kagan angle with the reference mechanism and the standard deviation of the depth estimation, respectively

et al. 2015; Kawaguchi et al. 2015) was established after 2012 and provides real-time broadband seismometer observation data with a much better quality than popup-type OBSs as the seismometers are buried beneath the seafloor (Araki et al. 2013). Using these data, several sVLFE episodes were investigated (Nakano et al. 2016, 2018; Toh et al. 2020); these data provide much more precise source locations of sVLFEs compared with landbased observations. Furthermore, geodetic observations based on pore pressure changes observed at several hundreds of meters below the sea floor in a bore hole revealed the repetition of large-to-small-scale short-term slow-slip events beneath the Kumano-nada area (Araki et al. 2017; Ariyoshi et al. 2021).

A short-term slow-slip event (SSE) with tectonic tremor and sVLFE activity occurred in Kumano-nada, starting in December 2020 and continuing until the middle of January 2021 (Araki et al. 2021; Japan Meteorological Agency 2021). In this study, we investigate the spatio-temporal distribution of the sVLFE activity during this SSE using DONET broadband seismometer data. We discuss the variations in the regional characteristics of the sVLFE activity based on their relationship with past activity and structural heterogeneities, which are thought to be related to the seismogenic status, such as the pore pressure along the plate interface and the topographic heterogeneities of the subducted slab at the shallow (updip side of the) transition zone.

Methods

We determined the CMT of the sVLFEs using the method of Nakano et al. (2008) (the SWIFT system), which performs a waveform inversion in the frequency domain to determine the source location, fault-orientation parameters, and moment magnitude of the earthquakes. We assumed a pure double-couple source mechanism. Fitting synthetic waveforms to the observed waveforms for each frequency component, we obtained the best-fitting faultorientation parameters and the location of the source centroid. Both the synthetic waveforms and the sourcetime functions were obtained via an inverse Fourier transform of the estimated parameters in the frequency domain. The moment magnitude was obtained by fitting step-like functions to the obtained source-time function in the frequency range used for the analysis. The waveforms obtained from broadband seismometers (CMG-3TEBB) at each DONET station were used in this study.

The setting for the analyses is the same as that of Nakano et al. (2018). We detected the signals by visually inspecting band-pass-filtered waveforms from the continuous records. The waveforms when the sVLFE signals were detected were band-pass-filtered between 0.03 and 0.05 Hz and then decimated to a sampling interval of 2 s. We used a total data length of 256 s for the inversion. Due to the relatively larger noise level of the horizontal components compared with the vertical components, we set the weight of the horizontal components to one-tenth of that of the vertical components in most cases.

The synthetic waveforms were calculated assuming the one-dimensional velocity model representing the study area (Nakano et al. 2013). The best-fitting source location was obtained via a grid search with a horizontal spacing of 0.01° in latitude and longitude and a vertical (depth) spacing of 1 km. We first determined the source centroid location using velocity seismograms and then estimated the moment tensor at that location using displacement seismograms. Additional file 1: Fig. S1 presents an example of a CMT inversion and displacement waveform fitting for an Mw 3.1 event on December 20, 2020.

We conducted CMT inversions for 681 events that were observed at three or more stations and contained at least one vertical component. Then, we selected the events for discussion using the following criteria: (1) an estimated Mw larger than 3; (2) residuals for the waveform fitting of less than 0.3; (3) residuals for the source—time function of less than 0.1, and (4) at least five waveforms being included in the inversion. Events with Mw<3 were excluded from the analysis because their detection capability was not homogeneous due to the observational localization within the study area. We employed the bootstrap method (Efron and Tibshirani 1994) to estimate the standard errors of the source locations and

the focal mechanisms for the selected 290 events. Using 500 bootstrap replications, in which the waveform traces were resampled at random and duplications were not discarded, we estimated the errors of the CMT inversion.

Results

As a result, we obtained 290 CMT solutions of the sVLFEs. The focal depths of most of the sVLFE are between 5 and 8 km, which is close to the depth of the plate boundary in this area (Nakanishi et al. 2018). The average source location errors were 0.03° in both latitude and longitude and 1.3 km in depth. The average errors of the plunge of the P-, T-, and B-axes were 34°, 32°, and 16°, respectively.

To identify the fault plane where the sVLFEs occur, we examined the CMT solutions. Based on the many structural studies along the Nankai Trough subduction zone (e.g., Nakanishi et al. 2018) and the maximum horizontal direction from the borehole breakout analysis (Lin et al. 2016), we assumed that the strike, dip, and rake angles for typical thrust earthquakes along the plate interface in this study area are 240°, 6°, and 90°, respectively, in Kumano-nada. We computed the Kagan angles (Kagan 1991) between the sVLFE CMT solutions and a typical interplate thrust. The Kagan angle evaluates the difference between two CMT solutions with an angle between 0° and 120°. This angle was smaller than 30° for most of the sVLFEs (Fig. 1b). Therefore, most of the sVLFEs that occurred during this episode are likely low-angle thrust-type events consistent with the plate boundary. In addition, we compared the average focal depth and its standard deviation obtained via the bootstrap method with the depth of the plate boundary model (Nakanishi et al. 2018) (Fig. 1c). There is a tendency for sVLFEs with smaller Kagan angles to be located at positions 1 km shallower than the plate boundary. Because the plate boundary model of Nakanishi et al. (2018) shows the depth of the top of the oceanic crust, layer 2, their depth model in this study is relatively deeper than the top of the subducted sediment and the actual plate interface, which corresponds to the plate boundary fault. Furthermore, both the spatial extent of sVLFE distribution along-dip direction (20–30 km) and dominant focal depth (6–8 km) are well explained by the $\sim 6^{\circ}$ dipping layer, consistent with the plate interface rather than that of splay faults. Therefore, we conclude that most of the detected sVLFEs occur along the plate interface, although we could not reject the possibility that a part of sVLFE occur along the splay faults.

sVLFE activity was also observed in 2009, 2015, and 2016 in the active area of this episode (Fig. 2a). The sVLFE distribution during this episode can be divided into two major parts: the eastern (E) and western (W)

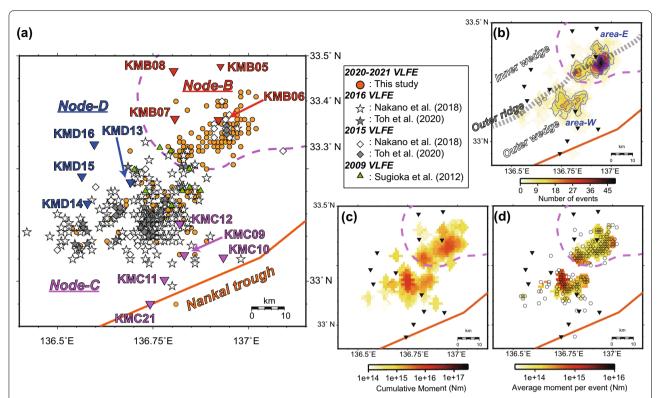


Fig. 2 Details of the sVLFE distribution. **a** Spatial distribution of the sVLFEs obtained in this and the previous studies. The DONET node and station codes are also shown. **b** Heatmap of the sVLFE activity for the entire episode. The background color and blue contours indicate the event number within 0.03° at each point. The contour interval is 5. The locations of the outer ridge, outer wedge, and inner wedge based on the bathymetry map are also shown. **c** Distribution of the cumulative moment release amount at each point. **d** Distribution of the moment release amount per event at each point. The open circles indicate the sVLFEs detected in this study. Note that only the areas where the event number within 0.03° larger than 5 are shown

areas in Figs. 1 and 2b, respectively. The E area is located south of the KMB stations, whereas the W area is located between the KMC and KMD stations. Counting the number of sVLFEs that occurred within 0.03° of the grid points that are spaced 0.01° horizontally, which corresponds to the average source location errors in horizontal direction and the spacing of the grid search, respectively, the most active region is east of the E area, south of KMB06 (Fig. 2b). This location corresponds to the 2015 activity. The cumulative moment of the sVLFEs in the E and W areas shows no significant difference, even though there is a maximum near KMD13 on the western side (Fig. 2c). Thus, the moment release per event is larger in the W area than in the E area (Fig. 2d).

Next, we plotted the sVLFE source locations in the along-trough and along-dip directions (Fig. 3a). In this study, time is given as Japanese Standard Time (UTC+9). We find that the activity can be divided into several stages with different migration patterns. The spatial distribution of the relative number of sVLFEs for each stage is presented in Fig. 4. The characteristics of the activity for each period are summarized as follows.

Stage 1: December 6-10, 2020

The first sVLFE in this episode occurred at 21:12 JST on December 6, 2021, in the E area. For the next 5 days, the activity was confined in an area with a radius of approximately 5 km in both the along-dip and along-trough directions around the starting point (Figs. 3a and 4a). This area corresponds to the area of sVLFE activity observed in October 2015 (Fig. 2a; Nakano et al. 2018; Toh et al. 2020).

Stage 2: December 11-12, 2020

The activity area expanded southwestward parallel to the trough axis, and relatively active sVLFEs were observed south of KMB07 (Figs. 3a and 4b). sVLFEs were not detected in this area; however, some activity was observed in March 2009 and April 2016 (Fig. 2a; Sugioka et al. 2012; Nakano et al. 2018; Toh et al. 2020). The activity area did not expand in the along-dip direction (Fig. 3b).

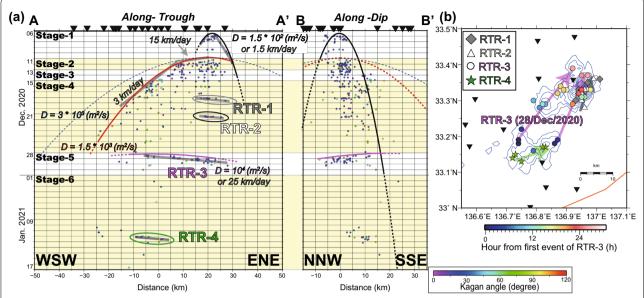


Fig. 3 Spatio-temporal distribution of the sVLFEs. **a** Along-trough and along-dip directions. The definition of these directions is presented in Fig. 1a. The white and yellow background colors indicate the periods of each stage. The circles indicate the projected locations of the sVLFEs with the color indicating the Kagan angle with respect to the reference focal mechanism shown in Fig. 1b. **b** Map view of the spatial distribution for rapid tremor reversals (RTRs) with different symbols for each episode. Only sVLFEs with Kagan angles with respect to the reference focal mechanism of less than 30° are plotted. The color of the circles (RTR-3 events) indicates the elapsed time from the first RTR-3 event. Gray, pink, and green vectors indicate the approximate migration direction for RTR-1 and 2, RTR-3, and RTR-4, respectively. Other symbols are the same as in Fig. 2b

Stage 3: December 13-14, 2020

sVLFE activity was observed for the first time in the W area (Fig. 4c and g) during this stage, and the active area extended southward, with continuing activity in the area of Stage 2, located south of KMB07 (Fig. 4b). This area is part of the sVLFE active areas in March 2009 and April 2016 (Fig. 2a; Sugioka et al. 2012; Nakano et al. 2018; Toh et al. 2020). We can confirm that this southward extension of the active area included extensions in both the along-dip and along-trough directions (Fig. 3a and b).

Stage 4: December 15-27, 2020

The active area further extended to the southwest, in the along-trough direction, filling the entire W area (Fig. 3a). However, the number of sVLFEs west of 136.7° E was much smaller compared with the activity in 2016 (Fig. 2a; Nakano et al. 2018). In the along-dip direction, the active area expanded toward the outer ridge (Fig. 4d). In the E area, the activity was not constant in time; swarm-like activity migrating to the northeast occurred on December 18 and 21. The activity south of KMB07 became inactive in areas where intensive activity had occurred in Stages 2 and 3 (Fig. 4d).

Stage 5: December 28-31, 2020

A pronounced northeastward migration was observed across the W and E areas (Fig. 3a). The activity during this stage occurred in an area that had already been activated in the previous stages, and there was no extension of the active area (Fig. 4e).

Stage 6: January 1-17, 2021

During this stage, no sVLFEs were observed in the E area (Fig. 4f and g). The overall activity was low; however, a swarm was observed on January 12 (Fig. 3a) in the W area. Even though the total number of sVLFEs was small, the active area appears to have extended close to the trough axis (Fig. 4f). Because no sufficiently large sVLFEs were observed to determine the focal mechanism after January 18, 2021, we defined the end of this stage as January 17, 2021. However, there were many sVLFE-like waveforms that were only observed at KMC21, especially from the middle to the end of January 2021.

Discussion

Location of the sVLFE clusters

The W area is located offshore between the outer ridge and the outer wedge regions (Fig. 2b). Based on tectonic surveys, this region has a thick shear zone resulting from

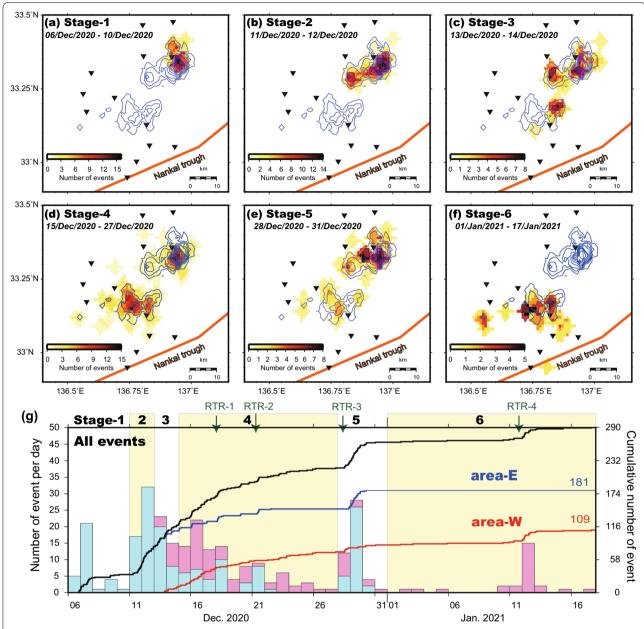


Fig. 4 Heatmap during this sVLFE episode for **a** Stage 1, **b** Stage 2, **c** Stage 3, **d** Stage 5, and **f** Stage 6. Other symbols are the same as in Fig. 2b. **g** Histogram of the sVLFEs. The height of the bars indicates the number of earthquakes per day, and the colors within the bars indicate the breakdown of the number of sVLFEs by area: eastern (E; sky-blue) and western (W; pink). The black, blue, and red lines are the cumulative number of sVLFEs in all catalogs, the E area, and the W area, respectively

the accumulation of underthrust sediment near the plate boundary (e.g., Tsuji et al. 2014). Full-wave inversions of the active seismic data (Kamei et al. 2013) and receiver function analyses (Akuhara et al. 2020) suggest that this thick shear zone is rich in fluid. Based on these previous studies, we considered that the existence of pore fluids could have promoted sVLFE activity in the W area during this episode. Shiraishi et al. (2020) proposed that

the distribution of sVLFE activity is controlled by the subduction of small-scale ridges. The most active part of the W area corresponds to the area where an sVLFE cluster was observed during the 2016 episode; these events were located on the down-dip side of a subducted ridge. This indicates that the dominant sVLFE region might be controlled by structural heterogeneities, such as the geometry of the plate interface, and that structural

heterogeneities cause micro-scale heterogeneities of the pore fluid distribution.

The outer wedge up-dip of the E area has a thin shear zone according to the MCS reflection survey (Fig. 8 of Hendriyana and Tsuji 2021). Hendriyana and Tsuji (2021) analyzed in detail tremors that occurred in 2015 and 2016 and proposed that the difference in the thickness of the share zone controls the tremor activity; tremors did not directly occur below the outer wedge in the E area, which has a thin shear zone. Toh et al. (2020) hypothesized that the absence of sVLFE activity up-dip of the E area is due to the presence of the paleo-Zenith Ridge, which suppresses fluid flow from down-dip, and that this ridge forms a fracture network on the upper plate. Our results do not contradict either hypothesis. In addition, if the existence of the subducted paleo-Zenith Ridge suppresses the fluid flow from down-dip, as proposed by Toh et al. (2020), the plate interface beneath the outer ridge area should accumulate fluid. In this case, the fluid from down-dip does not reach the outer wedge area. This heterogeneous distribution of fluids might be related to the active sVLFEs at the outer ridge, as well as the inactivity at the outer wedge in the E area.

Migration of sVLFE activities

Slow earthquakes, including sVLFEs, often show migration, and most researchers believe that this is due to the diffusion of pore fluid or stress (e.g., Ide 2010; Kato and Nakagawa 2020); however, constant velocity migration sometimes occurs (e.g., Yamashita et al. 2015). The diffusion coefficient D is used to express the rate of the spatial evolution as \sqrt{Dt} , where t denotes the time. The April 2016 sVLFE activity can be well fitted with $D=3\times10^3~\text{m}^2~\text{s}^{-1}$ (the blue dotted line in Fig. 3a) or 4 km day⁻¹ in both the along-trough and along-dip directions (Nakano et al. 2018).

In the activity during Stage 1, in the E area, studied here, $D=1.5\times 10^2~{\rm m}^2~{\rm s}^{-1}$ (the black line in Fig. 3a) or 1.5 km day⁻¹ fits the expansion front of the activity area well in both the trough-parallel and trough-orthogonal directions (Fig. 3a and b). During Stages 2–4 of the activity in the W area, the spatio-temporal distribution of the sVLFEs projected in the along-trough direction can be fitted with $D=1.5\times 10^3~{\rm m}^2~{\rm s}^{-1}$ (the red line in Fig. 3a) via diffusion. If we assume a linear velocity for the migration front, 15 km day⁻¹ for Stage 2 and 3 km day⁻¹ for Stages 3 and 4 are obtained. The migration in the along-dip direction is not as clear. As can be seen, the rate of area expansion is larger in the W area than in the E area.

The migration velocity may be related to the pore pressure and the energy released during the activity. Kano et al. (2018) carefully investigated deep tremor activities and demonstrated that, at locations where the migration

velocity is small, the released energy per event is small, the pore fluid pressure is high, and the number of tremors is large, and vice versa. The E area had a slower migration velocity (Fig. 3a and b), lower released energy per event, and larger number of sVLFE occurrences compared with the W area (Fig. 2b and d). Even though we do not have sufficient information on the values of the fluid pressure, the fluid pressure may be higher in the E area than in the W area if we assume that the relationship obtained by Kano et al. (2018) applies here.

If the relationships between the number of events, moment release per event, and migration velocity observed in this study always hold at the same locations, the conditions for sVLFE occurrence, such as the fluid pressure and stress state, are defined by the location. However, the rate of area expansion is different from past activities even in the same activity area. For example, in the W area, the diffusion coefficient was slightly smaller than that observed in April 2016. The 2016 sVLFE activity was triggered by the April 1, 2016, off-Mie earthquake (Mw=6.5) on the down-dip side of the western active area (Nakano et al. 2018), whereas the episode investigated here occurred spontaneously. This difference might reflect a temporal change in the stress level or the coupling status around the plate boundary in the source area. Another possibility is that these activities migrated in opposite directions; the 2016 activity started at the western edge of the activity area (distance = -25 km in the along-trough direction plot of Fig. 3a). In this case, the migration velocity might also depend on the migration direction. Even though we cannot currently identify why the migration velocities are different, these observations provide a constraint on mechanical models of sVLFE occurrence.

Migrations with much higher velocities than the activity front toward the northeast, opposite to the direction of the activity area expansion, occurred in Stage 4, 5 and 6. This is similar to the rapid tremor reversal (RTR; Houston et al. 2011) observed in tectonic tremor activity. We refer to this migration as RTR in this study because of their similarities. The migration of RTR during stage 5 (RTR-3) is well fitted with a constant velocity of approximately 25 km day⁻¹ or a diffusion coefficient of $D = 10^4 \,\mathrm{m}^2 \,\mathrm{s}^{-1}$ (the pink line in Fig. 3a). Other RTR activities occurred in the E area during Stage 4 (RTR-1 and 2) and in the W area during Stage 6 (RTR-4), with locations close to the ending and beginning points, respectively, of the RTR-3 with very similar migration speeds (Fig. 3). Therefore, we assume that these swarms share the nature of the RTR-3. By taking a closer look at the RTR-3 using the source locations obtained in this study with Kagan angles of less than 30°, it can be observed that the migration consists of two groups on lines approximately 10 km

apart (Fig. 3b) and that their activities occurred simultaneously. These features suggest that the RTR-3 occurred with some width in the direction orthogonal to the direction of propagation. The occurrence of these RTR activities may indicate a temporal change in the propagation efficiency of the fluid pressure and/or the stress level during this episode or the existence of pore-pressure waves in the plate interface (Cruz-Atienza et al. 2018).

The RTRs-3 and 4 were also reported in a land-based analysis (Takemura et al. 2021), in which the migration velocity was twice as large as that in this study. This difference could be explained by the difference in the location accuracy between the two catalogs. When we compare our sVLFE catalog with that of Takemura et al. (2021) and consider common events as those with a difference in occurrence time within 10 s, 75 events can be matched. In general, the sVLFE distribution of these events based on the catalog of Takemura et al. is wider than that in our result, and the average horizontal differences are 0.06° and 0.07° in longitude and latitude, respectively. From this comparison, we conclude that the difference in the migration speeds estimated here and by Takemura et al. (2021) is the result of the different accuracies of the locations in the two catalogs.

Possible sVLFE activities close to the trough axis

The sVLFEs for which a CMT solution was accurately obtained in this study are primarily distributed in the area surrounded by stations of Nodes B, C, and D (Fig. 2). Activity south of the KMC stations close to the trough axis was rare. Only during Stage 6 were a few sVLFEs observed. In addition, the activity in this region was not detected during the past episodes in November 2015 or April 2016 (Nakano et al. 2018). Beneath the Node C stations, the low-velocity zone in the accretionary prism is thinner than that beneath the KMB and KMD stations (Tonegawa et al. 2017). Tonegawa et al. suggested that sVLFEs are activated in sporadically distributed low-velocity and mechanically weak volumes within the accretionary prism where fluids significantly reduce the shear strength of the faults. In that case, the sVLFE activity should be higher between the KMB and KMD stations than near the KMC stations, which is consistent with the sVLFE distribution during this episode and that in 2016 (Fig. 2a and b).

However, we observed low-frequency signals that were very similar to sVLFEs (Fig. 5a) at station KMC21, which is closest to the trough axis (Fig. 2a). Visual detections of similar signals during the sVLFE episode demonstrated that their activity peaked in the middle of January 2021, during Stage 6 just after RTR-4 (Fig. 3), and continued

until February 2, 2021 (Fig. 5b). One of these events corresponds to an ordinary earthquake detected by the Japan Meteorological Agency; however, others do not. As these signals were not detected at other stations in most cases, we could not estimate their locations or focal mechanisms. However, these observations imply the occurrences of small-scale sVLFEs close to the trough axis. Because the up-dip side of the sVLFE activity area is important for tsunami source predictions, this activity needs to be carefully monitored. From the correspondence between the SSE and sVLFEs (Nakano et al. 2016), the investigation of the up-dip end of the sVLFE activity is also important to determine how shallow of a depth the background SSE reached.

Conclusions

Based on broadband seismic waveforms obtained from seafloor observations, we determined the CMT solutions of sVLFEs that occurred in the Nankai Trough between December 2020 and January 2021. The main results are as follows:

- (1) The activity area of this episode was divided into two parts: the E and W areas. The activity started from the E area, where sVLFE activity was observed in 2015, and then expanded to the southwestern area, where sVLFE activity was observed in 2016.
- (2) The characteristics of the activity between the two major active areas are different: the E area is primarily under the outer ridge, whereas the W area is primarily under the area between the outer ridge and the outer wedge. The observed sVLFE activity pattern corresponds to the location of the subducted paleo-Zenith Ridge beneath the E area and the difference in the thickness of the shared zone in the outer wedge.
- (3) There are also differences in the number of sVLFEs, the magnitude of individual events, and the expansion migration velocity between the E and W active areas, which may reflect the differences in the fluid pressures in each region.
- (4) Several RTR-like sVLFE migrations were observed. The largest occurred across both the E and W areas, with a 10-km width in the direction perpendicular to the direction of propagation.
- (5) At one station near the trough axis, we observed a waveform that suggested a sVLFE. Because the waveform is rarely observed at other stations and the activity was concentrated in mid-January, it is possible that a small-scale sVLFE occurred near the trough axis in the latter half of the episode.

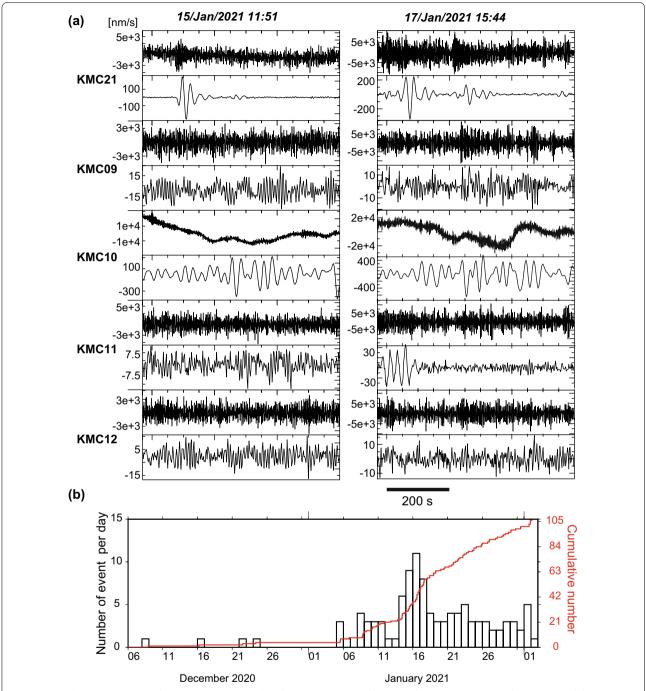


Fig. 5 sVLFE-like activity closes to the trough axis. **a** Examples of the observed waveform at Node C. For each station, the upper panel shows the original velocity waveform reduced to the trend, and the lower panel shows the band-pass-filtered (between 0.03 and 0.05 Hz) velocity waveforms (see details in text). The waveform at the KMC10 station has larger noise than those at other stations as this station is not buried beneath the seafloor. **b** Histogram of the sVLFE-like waveforms observed at KMC21

Abbreviations

sVLFE: Shallow very-low-frequency earthquake; SSE: Slow-slip event; CMT: Centroid moment tensor; OBS: Ocean bottom seismometer; DONET: Dense Oceanfloor Network System for Earthquakes and Tsunamis; RTR: Rapid tremor reversal

Supplementary Information

The online version contains supplementary material available at https://doi.org/10.1186/s40623-022-01573-x.

Additional file 1: Figure S1. Example of the result of the CMT inversion. (a) The observed and synthetic displacement waveforms at each component of each station are indicated in black and red, respectively. (b) Estimated CMT solution and parameters. The red line indicates the estimated moment function in the frequency range of the inversion analysis. The blue and green lines show the recovered source-time function based on the estimated moment function and its band-passed form in the frequency range of the inversion, respectively.

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Authors' contributions

YY: formal analysis, investigation, methodology, and writing of original draft. KA: formal analysis, investigation, review, and editing. SY: data curation, investigation, and resources. MN: formal analysis, methodology, software, review, and editing. TH: conceptualization, review, and editing. All authors read and approved the final manuscript.

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Availability of data and materials

DONET waveform data are available at https://doi.org/10.17598/NIED.0008. The program package "SWIFT" is available from M. Nakano upon reasonable request.

Declarations

Ethics approval and consent to participate

Not applicable.

Consent for publication

Not applicable.

Competing interests

The authors declare no conflicts of interest associated with this manuscript.

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