Bathymetric stripping corrections to gravity gradient components

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To allow for geophysical interpretation of observed gravity gradients, several corrections must be applied. In this article expressions for gravimetric forward modeling of bathymetric (ocean density contrast) stripping corrections to GOCE gravity gradient observables are evaluated numerically. The generic expression for the bathymetric gravitational potential utilizes a depth-dependent seawater density distribution model. The expressions are defined in their spectral representation by means of the bathymetric spherical functions which describe the global geometry of the ocean bottom relief. Numerical examples are given for the bathymetric stripping corrections to selected gravity field parameters computed with a spectral resolution complete to degree 360 of spherical harmonics. All computations are realized globally on the 1 arc-deg geographical grid at the mean satellite elevation of 250 km. The results reveal that the bathymetric stripping corrections to gravity gradients globally vary within $\pm 5 \times 10^{-9}$ s⁻². Extreme values apply mainly along the continental margins where the largest spatial bathymetric gravitation signal variations occur.

Key words: Bathymetry, forward modeling, GOCE, gravitational gradiometry, ocean density contrast.

1. Introduction

In gravimetric inverse methods for studying the lithosphere structure, the topographic, bathymetric, and additional corrections of all known anomalous mass density structures within the Earth's crust are applied to observed gravity data in order to model the unknown (and sought) density structure or density interface. In geophysics, this step is well known as gravity stripping (e.g., Hammer, 1963). The gravitational field generated by the ocean density contrast (relative to an adopted mean Earth's density) represents a significant amount of the gravitational signal to be modeled and subsequently removed from observed gravity data. Currently available global gravitational models (GGM) as well as global topographic and bathymetric data sets allow for relatively accurate numerical evaluation of topography-corrected and bathymetry-stripped gravity field parameters to a very high spatial resolution.

The GOCE gravity gradiometry satellite mission provides global and homogeneous data sets with well-known stochastic properties. It is thus expected that GOCE gravity field solutions will improve our knowledge about the Earth's inner density structure especially beneath oceanic and continental areas where seismic data are not yet available or their accuracy and spatial coverage is insufficient.

Novák and Grafarend (2006) evaluated numerically external gravitational fields of topographic and atmospheric masses by using spherical harmonic expansions. Tenzer *et al.* (2008, 2009, 2010) then computed globally the bathymetry-generated gravity field parameters by using the apparatus of the spherical harmonic analysis and synthesis. Novák (2010) computed globally the gravitational potential generated by the global ocean masses with a very high spatial resolution. In these studies a constant value of the ocean density contrast was adopted.

The actual seawater density variations due to salinity, temperature, and pressure typically range within 1020 and 1050 kg m⁻³, with most of this variation being due to pressure (Garrison, 2001). When the actual seawater density is approximated only by its mean value, relative inaccuracies up to about 2% were estimated in computed values of the bathymetric stripping corrections (Tenzer *et al.*, 2011). Since global bathymetric models are currently available to a very high accuracy and spatial resolution, the errors caused by approximating the actual seawater density by the mean value represent the largest contribution to the total error budget. These errors can reach up to 200 m² s⁻² and 16 mGal in terms of the gravitational potential and its radial derivative, respectively. The extreme values apply particularly to the computation areas situated over deepest oceans.

Gladkikh and Tenzer (2011) analyzed the oceanographic data of the World Ocean Atlas 2009 (WOA09) and the World Ocean Circulation Experiment 2004 (WOCE04). WOA09 products are made available by the NOAA's National Oceanographic Data Center (Johnson *et al.*, 2009). WOCE04 oceanographic data were provided by the German Federal Maritime and Hydrographic Agency (Gouretski and Koltermann, 2004). They used experimental data of salinity, temperature, and pressure to calculate the seawater density values based on the thermodynamic equation of state TEOS-10 for seawater (Millero *et al.*, 2008). The density values were then used to formulate an empirical model of the global seawater density distribution de-

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fined as a function of the ocean depth to account for density variations due to pressure. The comparison of the experimental and theoretical seawater density values revealed that the new empirical model approximates the above referenced seawater density distributions with the maximum relative error better than 0.6%, while the corresponding average error is about 0.1%. Tenzer *et al.* (2012a) utilized this empirical seawater density model for computing the bathymetric stripping gravity correction. In this study we adopt this empirical density model to compute accurately the bathymetric stripping corrections to gravity gradient components.

2. Theory

Tenzer *et al.* (2012a) derived the expression for the gravitational potential V generated by the ocean density contrast in the following form

$$V(r, \Omega) = \frac{\mathrm{GM}}{\mathrm{R}} \sum_{n=0}^{nax} \sum_{m=-n}^{n} \left(\frac{\mathrm{R}}{r}\right)^{n+1} \mathrm{V}_{nm} Y_{nm}(\Omega) , \quad (1)$$

where $R = 6371 \times 10^3$ m is the adopted mean Earth's radius, $GM = 3986005 \times 10^8$ m³ s⁻² is the geocentric gravitational constant, Y_{nm} stands for the spherical harmonic function of degree *n* and order *m*, and *nax* is the maximum available degree of spherical harmonics. The 3-D position is defined in the spherical coordinate system; where *r* is the geocentric radius and $\Omega = (\phi, \lambda)$ denotes the geocentric direction with spherical latitude ϕ and longitude λ . Bathymetric potential coefficients V_{nm} in Eq. (1) read

$$V_{nm} = \frac{3}{2n+1} \frac{\Delta \rho_0^w}{\rho^{\text{earth}}} \\ \times \left(F_{nm} - \frac{a_1 \beta}{\Delta \rho_0^w} R F_{nm}^1 - \frac{a_2 \beta}{\Delta \rho_0^w} R^2 F_{nm}^2 \right).$$
(2)

The nominal value of the ocean density contrast $\Delta \rho_0^w$ is defined as the difference between the reference crustal density ρ^{crust} and the seawater density ρ_0^w , i.e., $\Delta \rho_0^w = \rho^{\text{crust}} - \rho_0^w$. The value of the surface seawater density $\rho_0^w = 1027.91$ kg m⁻³ (Gladkikh and Tenzer, 2011) was adopted as the nominal seawater density. For the adopted value of the reference crustal density ρ^{crust} of 2670 kg m⁻³ (Hinze, 2003), the nominal ocean density contrast (at the zero depth) equals $\Delta \rho_0^w = 1642.09$ kg m⁻³. The adopted value of the Earth's mean homogeneous density in Eq. (2) is $\rho^{\text{earth}} = 5500$ kg m⁻³ (e.g., Novák, 2010). The parameters of the depth-dependent density term in Eq. (2) are: $\beta = 0.00637$ kg m⁻³, $a_1 = 0.7595$ m⁻¹ and $a_2 = -4.3984 \times 10^{-6}$ m⁻². The numerical coefficients F_{nm}, F¹_{nm} and F²_{nm} in Eq. (2) are defined as (Tenzer *et al.*, 2011)

$$\mathbf{F}_{nm} = \sum_{k=0}^{n+2} {\binom{n+2}{k}} \frac{(-1)^k}{k+1} \frac{\mathbf{D}_{nm}^{(k+1)}}{\mathbf{R}^{k+1}}, \qquad (3)$$

$$\mathbf{F}_{nm}^{1} = \sum_{k=0}^{n+2} \binom{n+2}{k} \frac{(-1)^{k}}{k+2} \frac{\mathbf{D}_{nm}^{(k+2)}}{\mathbf{R}^{k+2}}, \qquad (4)$$

$$\mathbf{F}_{nm}^{2} = \sum_{k=0}^{n+2} \binom{n+2}{k} \frac{(-1)^{k}}{k+3} \frac{\mathbf{D}_{nm}^{(k+3)}}{\mathbf{R}^{k+3}} \,. \tag{5}$$

The coefficients D_{nm} of the global bathymetric model (GBM) describe the geometry of the ocean bottom relief. The series $\Sigma D_{nm} Y_{nm}$ defines the surface spherical bathymetric function D_n of degree *n*. It reads (Tenzer *et al.*, 2010)

$$D_n(\Omega) = \frac{2n+1}{4\pi} \iint_{\Phi} D(\Omega') P_n(\cos \psi) d\Omega'$$
$$= \sum_{m=-n}^n D_{nm} Y_{nm}(\Omega) , \qquad (6)$$

where *D* is the ocean depth and P_n is the Legendre polynomial. Higher-order terms $\{D_n^{(i)}: i = 2, 3, 4...\}$ read

$$D_{n}^{(i)} = \frac{2n+1}{4\pi} \iint_{\Phi} D^{(i)}(\Omega') P_{n}(\cos \psi) d\Omega'$$

= $\sum_{m=-n}^{n} D_{nm}^{(i)} Y_{nm}(\Omega) ,$ (7)

where the symbol Φ denotes the full spatial angle. The components of the gravitational vector and Marussi gravitational gradient tensor, both generated by the ocean density contrast, can be readily derived from the expressions in Eqs. (1)–(7).

3. Numerical Examples

The GBM coefficients were used to compute the bathymetric stripping corrections to the Earth's gravitational potential and its first- and second-order derivatives with a spectral resolution complete to degree 360 of spherical harmonics. The computation was done globally on a 1 arc-deg grid at the mean elevation of 250 km. Statistics of all results are summarized in Table 1. The global maps of selected quantities: V, V_r , V_{rr} , $V_{\phi\phi}$ and $V_{\lambda\lambda}$ are shown in Figs. 1–3.

The bathymetric gravitational potential V, see Fig. 1, is everywhere positive. The maximum signal is over the largest ocean mass concentration (central Pacific Ocean).

The global map of V_r , see Fig. 2, revealed major structures of the ocean bottom relief. It is everywhere negative, with its absolute maxima distributed over oceanic basins and (partially) subduction zones in Pacific Ocean. The spatial distribution of V_r over oceanic areas also clearly revealed the features related to the oceanic divergent zones (i.e., mid-oceanic ridges). It was demonstrated in Tenzer

Table 1. Statistics of gravitational parameters generated by the ocean density contrast computed globally on a 1 arc-deg grid at the elevation of 250 km.

Parameter	Min	Max	Mean	RMS
V [m ² s ⁻²]	16078	27173	21604	2907
V_r [mGal]	-544	-128	-309	125
V_{ϕ} [mGal]	-287	194	-14	77
V_{λ} [mGal]	-221	246	0.0	66
V_{rr} [E]	-2.0	4.7	0.9	1.4
$V_{\phi\phi}$ [E]	-2.6	2.2	0.0	0.7
$V_{\lambda\lambda}$ [E]	-3.5	3.1	0.0	0.7
$V_{r\phi}$ [E]	-3.5	4.1	-0.1	0.8
$V_{r\lambda}$ [E]	-4.0	3.7	0.0	0.7
$V_{\phi\lambda}$ [E]	-2.6	3.5	0.0	0.5



Fig. 1. Gravitational potential V (m² s⁻²).



Fig. 2. Gravitational vector component V_r (mGal = 10^{-5} m s⁻²).

et al. (2012b), that the application of this correction is essential for the interpretation of the age of oceanic lithosphere (characterized by the formation of oceanic lithosphere along the mid-oceanic ridges, its further speeding and consequent subduction under the oceanic or continental crust along the oceanic subduction zones) which is attributed to mantle convection. The (absolute) values of V_r substantially decrease along the continental margins distinctively marking the boundary between the oceanic and continental lithosphere.

Whereas V_r is directly correlated with bathymetric depths, the maximum signal of V_{rr} corresponds with the largest spatial variations of the ocean bottom relief. This is seen in Fig. 3(a). The map of V_{rr} revealed major structures of the oceanic lithosphere. The small positive values are found along the oceanic divergent boundaries (mid-oceanic ridges). Over areas of the oceanic abyssal planes, these values further increase. The maxima correspond with locations of the oceanic subduction zones. Boundaries between oceanic and continental tectonic plates are also clearly distinguished (by small negative values) in the gravity map. The bathymetric corrections $V_{\phi\phi}$ and $V_{\lambda\lambda}$, see Figs. 3(b, c), revealed a pattern of the largest horizontal variations of bathymetric gravitational field with respect to the meridional and prime-vertical directions. The maximum positive







Fig. 3. Gravitational gradient components (a) V_{rr} , (b) $V_{\phi\phi}$ and (c) $V_{\lambda\lambda}$ (E = 10^{-9} s^{-2}).

and negative values of $V_{\phi\phi}$ are coupled along the continental margins with prevailing latitudinal directions. A similar pattern of the gravity signal is seen in the global map of $V_{\lambda\lambda}$, but in this case with prevailing meridional direction.

4. Summary and Concluding Remarks

We have derived and applied spectral expressions for computing the bathymetric stripping corrections to gravity field parameters. The numerical examples were given globally on a 1 arc-deg grid computed at the mean satellite elevation of 250 km.

We demonstrated that the maxima of the bathymetric potential V and its radial derivative V_r correspond with the largest seawater accumulation in Pacific Ocean. The map of V_{rr} reproduces major structures of the oceanic lithosphere. The spatial distributions of the horizontal components $V_{\phi\phi}$ and $V_{\lambda\lambda}$ are more complex reflecting the largest bathymetric gravitational signal variations with respect to the coordinate directions. Their extreme values are found along the continental margins again with prevailing either south-north or east-west directions. Compared to V_{ϕ} and V_{λ} , the maximum signal of $V_{\phi\phi}$ and $V_{\lambda\lambda}$ along a particular continental margin comprises both, the positive as well as negative values.

Whereas the application of V_r is important for modeling and interpretation of the refined gravity field obtained based on analysis of GRACE inter-satellite observables, the bathymetric stripping corrections V_{rr} , $V_{\phi\phi}$ and $V_{\lambda\lambda}$ are applied to GOCE gravity gradient measurements. GOCE gravity gradiometry data provide the accurate information about the Earth's gravity field especially at the medium spherical harmonics (somewhere between degrees 70–200). GRACE data provide the accurate information at the longwavelength part of the gravitational field (up to degree of about 120). The combined inversion of GRACE and GOCE data (including additional geophysical constrains) is thus essential for a more robust and accurate recovery of the Earth's inner density structures.

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