

Improving geomagnetic field models for the period 1980–1999 using Ørsted data

Pascale Ultré-Guérard, Dominique Jault, Mioara Alexandrescu, and José Achache

Institut de Physique du Globe de Paris, 4 Place Jussieu, 75252 Paris Cedex 05, France

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The Danish satellite Ørsted is due to be launched in 1998, and should provide, for the first time since the Magsat mission (1979–1980), a dense and global coverage of the Earth's surface with vector measurements of the magnetic field. In this paper, we compare the expected error in the main field models computed for the 1970–1999 time interval using observatory data, with or without the a priori information given by the knowledge of the field at both Magsat and Ørsted epochs. This work is based on the reasonable hypothesis that the main field models derived from Ørsted data will be as accurate as the Magsat models. The a priori information given by the Magsat and Ørsted models is based on a linear behaviour of the rate-of-change of the field throughout this period, plus a noise level which can be estimated as a function of time and degree from past field changes. The expected error in the models computed for the 1980–1999 period with a priori information appears to be significantly smaller than the expected error in the models computed without this information. This result is related to the heterogeneous distribution of the observatories over the Earth surface. Consequently, when the Ørsted data is available, improved models can be computed for the 1980–1999 period particularly in regions without observatory data. This method with a priori information may allow the use of the same set of observatories throughout the entire period. Indeed, our method alleviates the requirement of a very dense data distribution.

1. Introduction

Because of the heterogeneous distribution of observatories over the Earth's surface, main field models are plagued with large errors as harmonical analysis degree and order values become larger when they are computed using only observatory data (Alexandrescu *et al.*, 1994). Furthermore, Alexandrescu *et al.* (1994) show that, even for the smallest degrees, these errors are large as indicated by the covariance matrices. Indeed, global field models can be computed applying Gauss potential field theory, but for regions with few observatories (i.e., the Pacific, Indian, and most of the Atlantic Oceans) the field is not accurately determined. The Magsat satellite, launched in November 1979, provided accurate vector measurements of the Earth's magnetic field with a dense and homogeneous distribution. Thus, the main field has been accurately modelled for the 1980.0 epoch (e.g., Langel and Estes, 1985; Bloxham *et al.*, 1989; Cohen, 1989). Estimating the crustal biases of the observatories has also enhanced the accuracy of main field models for other epochs (Langel *et al.*, 1982; Gubbins and Bloxham, 1985; Langel and Estes, 1985; Bloxham *et al.*, 1989). However, the Magsat mission has given almost no information on the geomagnetic field SV (Secular Variation—the first time derivative of the field). Thanks to the Danish Ørsted satellite, which is scheduled to be launched in 1998, we may obtain for the first time since Magsat, a global and dense coverage of the Earth's surface with accurate vector measurements of the magnetic field. This mission should be closely followed by other satellite

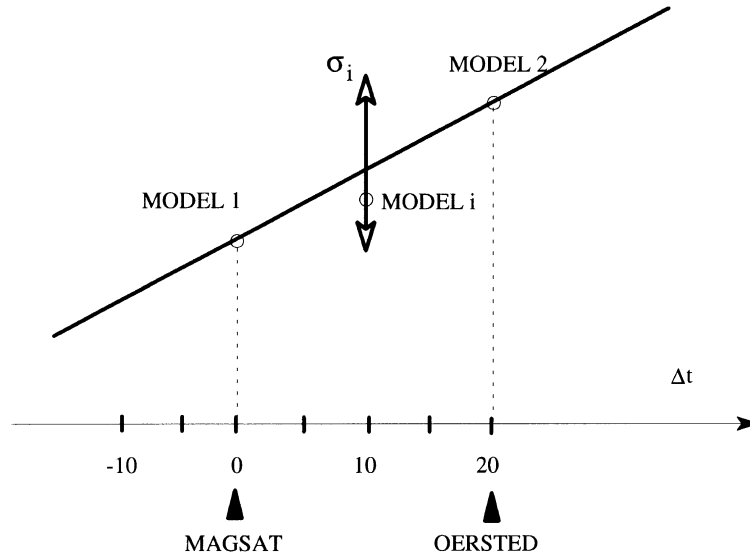
missions such as CHAMP, SAC-C, Sunsat, FedSat, DMSP Block 5, NPOESS over the coming years. Hopefully, it will be possible to compute accurate models of the field from 1999 onwards. Obviously, knowledge of the field at the epochs of Magsat and Ørsted will allow the computation of the linear component of the magnetic field time-variation between 1980 and 1999. In this study, we show that the simultaneous use of Magsat and Ørsted data will improve our knowledge of SV, as well as our knowledge of the higher frequencies of the time-variations of the geomagnetic field around the period 1980–1999.

2. Method

2.1 Inverse problem

Our objective is to show how the knowledge of the geomagnetic field at Magsat and Ørsted epochs (respectively 1980.0 and 1999.0) will improve the computed models using observatory data throughout the 1980–1999 period. In doing so, coherence between the different data sets is expected. The discrepancies in field values between Magsat models and observatory data have been attributed to local crustal field at the observatories. These biases are thought to stay constant with time. This is confirmed in a recent paper in which observatory data corrected with biases calculated during the Magsat epoch are shown to be compatible with data from the POGS satellite for the period 1991–1993 (Ultré-Guérard and Achache, 1997).

The method applied here is based on a least-squares inversion with a priori information (see e.g., Tarantola and Valette, 1982; Langel, 1987). A model is computed using the a priori information given by the linear time-variation of the field between Magsat and Ørsted. The inversion consists

Fig. 1. Definition of the time intervals Δt .

of minimizing the following sum:

$$\begin{aligned}
 \Sigma^2 = & \sum_{N_{\text{coef}}} W_{\text{Magsat}} \left(g_{\text{Magsat}}^{\text{model}} - g_{\text{Magsat}}^0 \right)^2 \\
 & + \sum_{N_{\text{coef}}} W_{\text{Computed}} \cdot \left(g_{\text{Computed}}^{\text{model}} - \frac{t_{\text{Ørsted}} - t_{\text{Model}}}{t_{\text{Ørsted}} - t_{\text{Magsat}}} g_{\text{Magsat}}^{\text{model}} \right. \\
 & \quad \left. - \frac{t_{\text{Model}} - t_{\text{Magsat}}}{t_{\text{Ørsted}} - t_{\text{Magsat}}} g_{\text{Ørsted}}^{\text{model}} \right)^2 \\
 & + \sum_{N_{\text{coef}}} W_{\text{Ørsted}} \left(g_{\text{Ørsted}}^{\text{model}} - g_{\text{Ørsted}}^0 \right)^2 \\
 & + \sum_{N_{\text{mes}}} \left[W_{\text{vec}}^X \left(X_{\text{Computed}}^{\text{model}} - X^{\text{Obs}} \right)^2 \right. \\
 & \quad + W_{\text{vec}}^Y \left(Y_{\text{Computed}}^{\text{model}} - Y^{\text{Obs}} \right)^2 \\
 & \quad \left. + W_{\text{vec}}^Z \left(Z_{\text{Computed}}^{\text{model}} - Z^{\text{Obs}} \right)^2 \right] \quad (1)
 \end{aligned}$$

where t_{Magsat} and $t_{\text{Ørsted}}$ are the times of Magsat and Ørsted missions respectively, t_{Model} denotes the time for which the model is calculated. Time can be before, between, or after the two missions. $g_{\text{Magsat}}^{\text{model}}$, $g_{\text{Computed}}^{\text{model}}$ and $g_{\text{Ørsted}}^{\text{model}}$ define the Gauss coefficients of the models computed at t_{Magsat} , t_{Model} and $t_{\text{Ørsted}}$ epochs respectively. g_{Magsat}^0 and $g_{\text{Ørsted}}^0$ are the a priori models computed at Magsat and Ørsted epochs, which give the linear trend of the rate-of-change between the Magsat and Ørsted epochs. $X_{\text{Computed}}^{\text{model}}$, $Y_{\text{Computed}}^{\text{model}}$ and $Z_{\text{Computed}}^{\text{model}}$ are the components of the field as computed by the model $g_{\text{Computed}}^{\text{model}}$. X^{Obs} , Y^{Obs} and Z^{Obs} are the 3 components of the geomagnetic field measured at the observatories. W_{Magsat} , W_{Computed} , $W_{\text{Ørsted}}$, W_{vec}^X , W_{vec}^Y , W_{vec}^Z are the weights (see section below) applied to the different terms. All the models are limited to degree and order 8 in order to compare our computed model with models derived from only observatory data. The coefficients of the field at Magsat and Ørsted epochs are unknown but the

weights entering the first and third terms on the right hand side of the equation are so large that these coefficients can be thought of as being fixed. The model is constrained not to depart significantly from the linear trend given by Magsat and Ørsted models in the second term of Eq. (1). Constraints given by the observatory measurements are incorporated in the fourth term. At the epoch t_{Model} , the field is assumed to be measured at 190 existing observatories. For comparison, the inversion is also done for a hypothetical case where 190 ground data points are evenly distributed at the Earth's surface.

2.2 Choice of the weights

Making the reasonable hypothesis that the models derived from Ørsted data will be as accurate as the models derived from Magsat data, the weights for Magsat and Ørsted models (W_{Magsat} and $W_{\text{Ørsted}}$) are taken to be equal and are estimated for each Gauss coefficient as the inverse of the variance of the model computed with Magsat data. The weights for the observatory vector data are taken with respect to the value estimated by Langel *et al.* (1996), i.e.:

$$W_{\text{vec}}^C = \frac{1}{\sigma_{\text{vec}}^2(C)}$$

with:

$$\sigma_{\text{vec}}(X) = \sigma_{\text{vec}}(Y) = 26 \text{ nT}$$

$$\sigma_{\text{vec}}(Z) = 32 \text{ nT},$$

where the σ_{vec} are defined as the mean deviations of the measured components at the observatories from the values given by the model computed by Langel *et al.* (1996). These deviations do not include the crustal biases which are computed as unknown parameters during the inversion of the satellite and observatory data.

A statistical study performed for the interval 1900–1990 with existing models (Bloxham and Jackson, 1992) taken every 5 year shows that the rate-of-change of the field, on

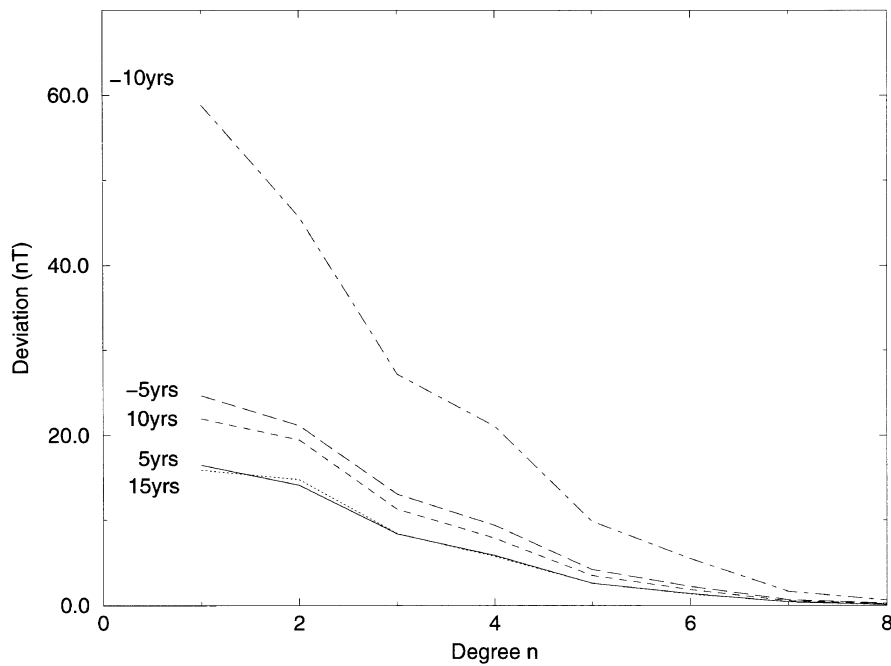


Fig. 2. Deviation σ (see text) averaged for the 1900–1990 period versus the spherical harmonic degree n for different time intervals $\Delta t = -10, -5, 5, 10$ and 15 yrs.

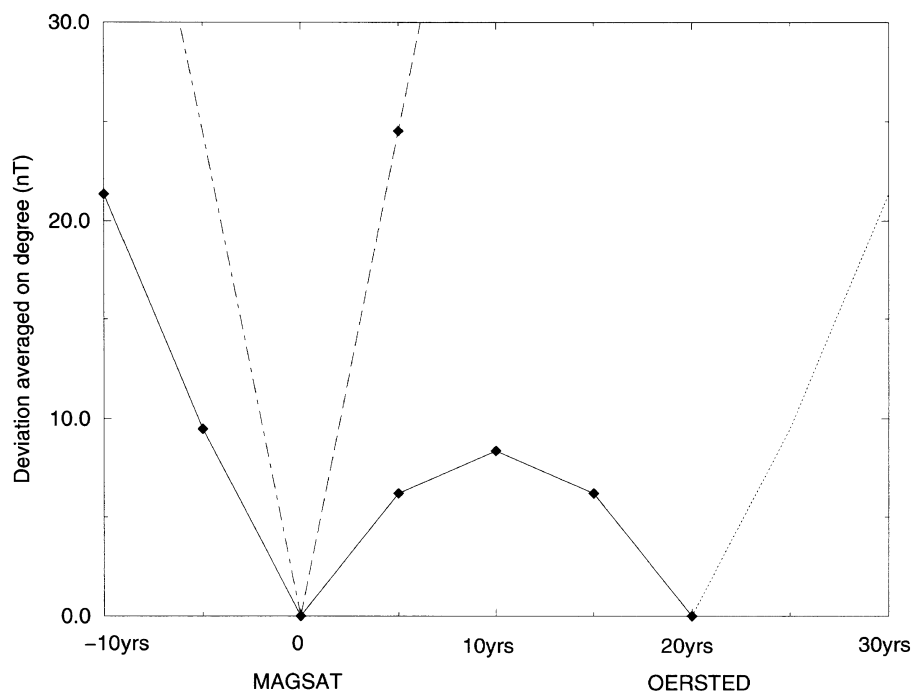
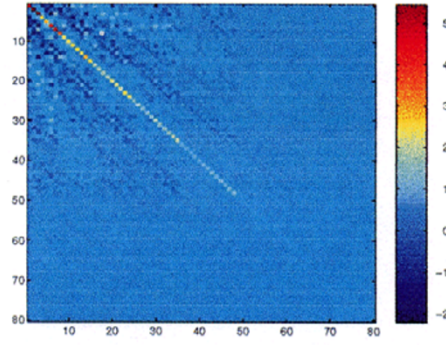


Fig. 3. Deviation σ averaged as a function of time (solid line). The deviation corresponding to Magsat proximity alone is given for comparison (dashed line). The dotted and dotted-dashed lines are symmetric about the computed lines.

the decade time-scale, can be described with a linear trend plus an estimated noise level. We checked that this first order description is valid for periods including geomagnetic jerks of global extent (e.g., 1969, 1978). A more detailed study of those periods requires other approaches. The jerks can be expressed in the form of two second degree polynomials of

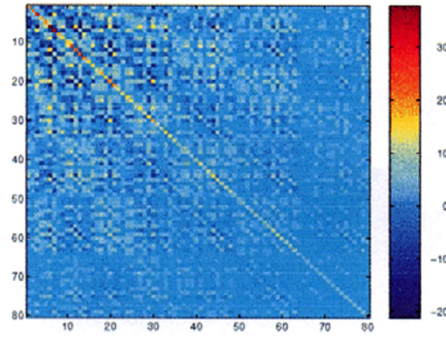
time with a sudden change in curvature at the time of the event (e.g., Courtillot *et al.*, 1978; Achache *et al.*, 1980; Ducruix *et al.*, 1980). Or, they can be referred to as singularities and defined as discontinuities of some α^{th} derivative of the signal (α —the “regularity” of the singularity being not necessarily an integer) (Alexandrescu *et al.*, 1995, 1996). However,

WITH *a priori* information



$$R = 9.5$$

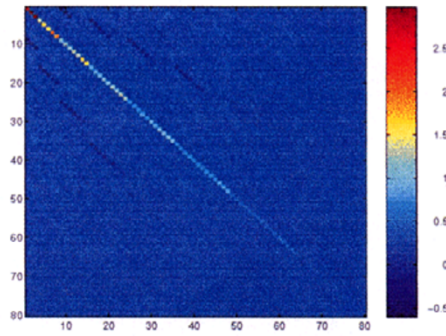
WITHOUT *a priori* information



$$R = 4$$

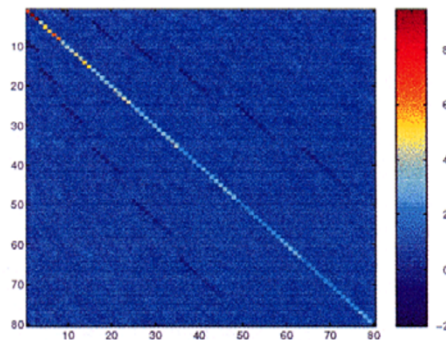
Fig. 4. Covariance matrices of the computed model obtained for an existing and uneven distribution of observatories, with and without the *a priori* information; g_1^0 is represented in the left upper part of each matrix, the degree and the order increases to the right and downwards. Units of the covariance matrices are $(\text{nT})^2$. The ratio R (see text) is given in both cases.

WITH *a priori* information



$$R = 31.5$$

WITHOUT *a priori* information



$$R = 27.5$$

Fig. 5. Covariance matrices of the computed model obtained for an ideal and even distribution of observatories, with and without the *a priori* information. Units of the covariance matrices are $(\text{nT})^2$. The ratio R (see text) is given in both cases.

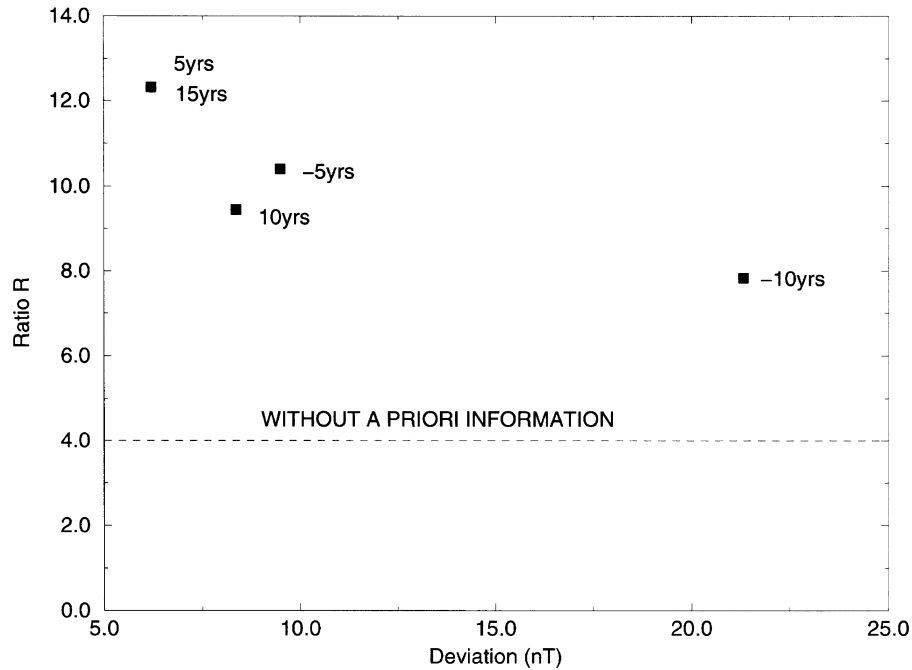


Fig. 6. Values of the ratio R as a function of the deviation σ for different time intervals Δt .

these approaches are not needed for our purpose. Our description of the rate-of-change of the field is also justified by the time constants of the geomagnetic field which are of the order of several hundred years for the axial dipole and of a couple of hundred years for the non-dipole terms (Hulot and Le Mouél, 1994). The discrepancy between an actual model and a linear fit to two given end models 20 years apart is computed as a function of the degree n as follows:

$$\sigma_n = \left(\frac{1}{2n+1} \sum_{m=0}^n (\delta g_n^m)^2 + (\delta h_n^m)^2 \right)^{\frac{1}{2}}, \quad (2)$$

where δg_n^m and δh_n^m are the deviations of the coefficients of the chosen model (“model i”) from the linear interpolation between the coefficients of the two end models. It is calculated as a function of the time interval between the epoch of the model and the epoch of the first assumed known model ($\Delta t = -10, -5, 5, 10$ and 15 years: see Fig. 1). The calculation is performed for each set of two models, separated by 20 years, and the estimates are averaged for the period 1900–1990. The calculated deviation is compared to the degree for the different time intervals in Fig. 2. This figure shows that the deviation is greater for the negative values of Δt . Indeed, “model i” is outside of the interval between models 1 and 2 where the linear trend is defined. The deviation averaged over degree for different time intervals Δt is given in Fig. 3. This figure also shows the deviation corresponding to the a priori information given by Magsat proximity alone, which supports the assumption of linear behaviour of the time-variations of the field.

The covariance matrix $(A^T W A)^{-1}$, where A is the Jacobian matrix and W is the matrix of weights, associated with the computed model is estimated and compared with the matrix obtained when only observatory data are used without the

a priori information. For each matrix, the ratio between the quadratic mean of the diagonal terms and the quadratic mean of the non-diagonal terms $R = \|\overline{(V)}_{ii}\| / \|\overline{(V)}_{ij}\|$ is also computed. Small values of R indicate large cross-correlations between the coefficients.

3. Results

The inversion is performed in the case where the time-interval Δt is equal to 10 years (this is the most unfavorable case for the time interval between Magsat and Ørsted epochs, see Fig. 3).

Firstly, the covariance matrix of the computed model in the case of the actual observatory distribution is presented in Fig. 4. The covariance matrix, obtained when the observatory data are inverted without a priori information, is given for comparison. In this case, the ratio R is increased by the a priori information (from $R = 4$ to $R = 9.5$).

Secondly, the same matrices are computed for the hypothetical case of an even distribution of observatory data (Fig. 5). In this case, the improvement is shown to be less significant. Indeed, the variances are similar with or without the a priori information and the ratio R is not very different as it varies from $R = 31.5$ in the first case to $R = 27.5$ in the second. These comparable values of R demonstrate that the a priori information obtained by the two sets of satellite data is so valuable given an uneven distribution of observatories.

Finally, Fig. 6 gives the different values of the ratio R when the same study is performed for different time intervals around the Magsat and Ørsted epochs. When the inversion is performed without a priori information the ratio is constant. Its value is also plotted for comparison (Fig. 6). It appears that using a priori information reduces the error on the computed model during the 40 years period around the Magsat and Ørsted missions.

4. Conclusion

The results of this study show a potential benefit to main field modelling by using Ørsted data. When Ørsted data are available, we will compute annual models of the 1980–1999 period, using the observatory data (annual means) and the main field models derived from Magsat and Ørsted data. Their coefficients will be estimated with the a priori information given by the linear rate-of-change of the field between Magsat and Ørsted epochs using the method presented above. The present study also shows that the models computed with the a priori information will be more accurate than the existing ones because of the uneven distribution of the observatories over the Earth's surface. The knowledge of the field in the regions where there is no ground data can be much improved. At the present time, reference field models are computed by using data available from various origins (observatories, repeat stations, surveys, aeromagnetic surveys, . . .) in order to have the best distribution at the Earth's surface. Thanks to Ørsted data and to the a priori information given by the linear time-variation of the field between Magsat and Ørsted, it will be possible to compute accurate models with a carefully selected data set, composed only of the most accurate and continuous records of the field. Indeed, if the data set is always the same for every model, the error will be systematic and will cancel in secular variation models. We expect secular variation models to be improved for a 40 year time interval around the Magsat and Ørsted satellite missions and maybe for a longer period if current planned satellite missions are realised in the future.

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P. Ultré-Guérard (e-mail: ultre@ipgp.jussieu.fr), D. Jault, M. Alexandrescu, and J. Achache