

# Deterministic and probabilistic seismic hazard analyses in Thailand and adjacent areas using active fault data

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Seismic hazards in Thailand and adjacent areas were analyzed mainly on the basis of geological fault data. We identified 55 active fault zones using remote-sensing data on earthquake source parameters derived from both active fault data and earthquake catalogues. We selected strong ground-motion attenuation models by comparing the application of several candidate models with strong ground-motion data recorded in Thailand. Both deterministic (DSHA) and probabilistic (PSHA) approaches were used—DSHA for the design of critical construction and PSHA for the design of non-critical construction. We also applied two frequency-magnitude models in the PSHA approach: the exponential magnitude distribution model and the characteristic earthquake model. The seismic hazard results obtained using the deterministic and probabilistic approaches are not equivalent. The resulting DSHA map reveals extremely high seismic hazard levels in some areas of Thailand and in surrounding countries, while the PSHA map reveals a seismic hazard distribution similar to that of the DSHA but with lower seismic hazard levels. The areas of high seismic hazard include countries neighboring Thailand, such as Myanmar, Laos, Vietnam, and Indonesia (Sumatra Island), and areas within Thailand itself, primarily those areas in northern, western, and southern Thailand that are dominated by active fault zones.

**Key words:** Seismic hazard analysis, deterministic method, probabilistic method, active fault, Thailand.

## 1. Introduction

There are a number of active fault systems in northern, western, and southern Thailand (e.g., Fenton *et al.*, 2003; Charusiri *et al.*, 2004; Wong *et al.*, 2005) (Fig. 1(a)). Thailand is also surrounded by other major earthquake sources, such as the great strike-slip Sagiang fault of central Myanmar (Bertrand and Rangin, 2003), a complex shear zone near the Laos-southwestern China border (Socquet and Pubellier, 2005), and the well-known Andaman subduction zone where the moment magnitude ( $M_w$ ) 9.0 Sumatra-Andaman earthquake occurred on 26 December 2004 (Petersen *et al.*, 2004). Instrumental earthquake records and historical earthquake information, including paleoseismological evidence (e.g., Fenton *et al.*, 2003; Charusiri *et al.*, 2004), all indicate that Thailand is an earthquake-prone area that should make provisions to mitigate potential seismic hazards.

In recent times, there have been few seismic hazard investigations that have focused on Thailand. Warnitchai and Lisantono (1996) and Palasri (2006) used the probabilistic approach to seismic hazard analysis by using recent seismicity data (i.e., from earthquake catalogues). Their results, however, may be characterized by a number of limitations because of the short history of instrumental recordings of

earthquakes. Because the recurrence interval of large earthquakes can be several hundreds to thousands of years, the time span covered by instrumental records is too short to represent the behavior of earthquake activity either along individual faults or in specific regions. It is currently accepted worldwide that paleoseismological information (i.e., active fault data) is important for evaluating seismic hazards (e.g., Atakan *et al.*, 2001; Gurbinar, 2005). This information, which is obtained from active fault investigations, can bridge the gap between instrumental and pre-instrumental data. Petersen *et al.* (2007) calculated the probabilistic seismic hazard in Southeast Asia (including Thailand and adjacent areas) using both paleoseismological and seismicity data. However, they used the data from only 15 fault zones in Thailand and two fault zones from neighboring countries (i.e., the Sagiang fault zone in central Myanmar and the Red River fault zone in northern Vietnam) to evaluate the earthquake sources. This apparent disregard of the earthquake source (i.e., active faults) may result in less accurate seismic hazard maps in terms of the number of earthquake source zones. Changes in how we regard earthquake sources, therefore, should be made in order to eliminate artifacts on seismic hazard maps.

Here, we first provide some background on the use of active fault data for analyzing seismic hazards in Thailand and neighboring areas. Due to the insufficiency of paleoseismological data along the fault segments, we adopted the strategy of treating each site-specific paleoseismological study equally for individual fault zones with the aim of analyz-

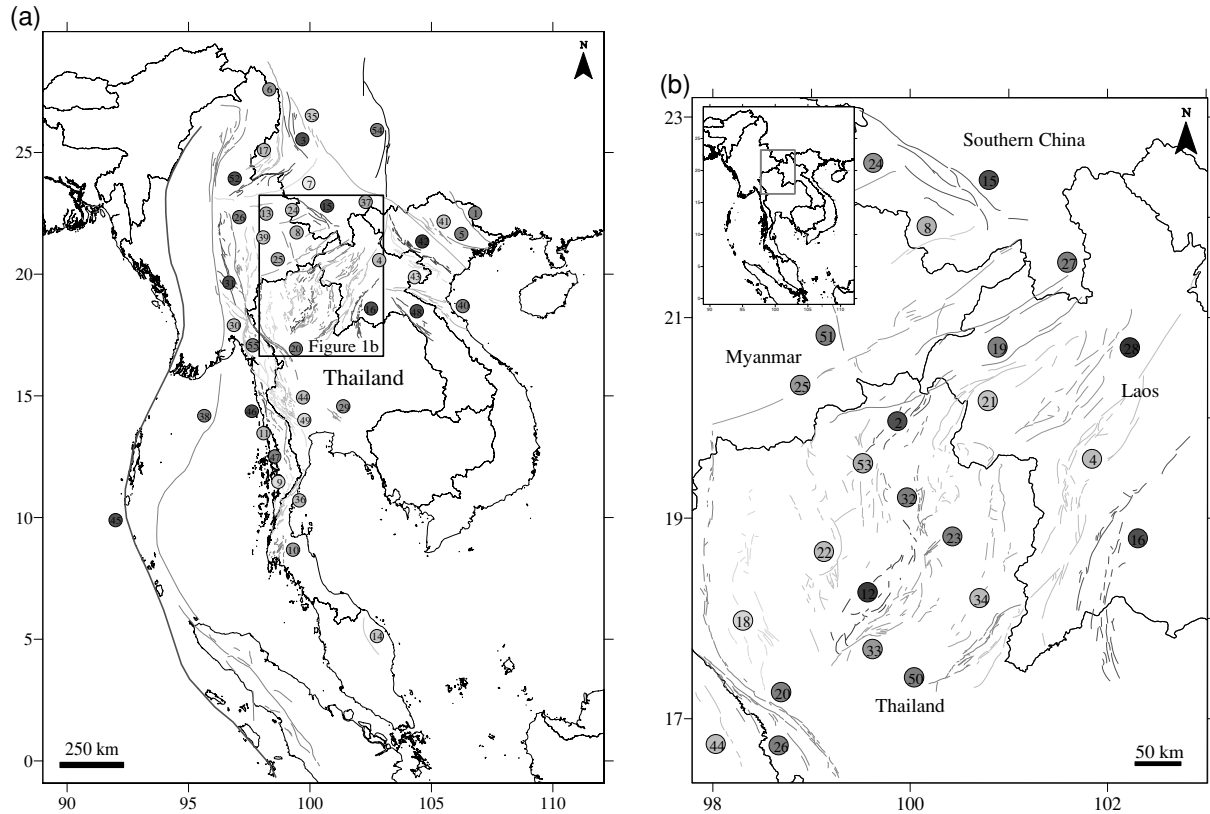


Fig. 1. (a) Active faults in Thailand and adjacent areas interpreted from remote sensing data (IKONOS, LANDSAT, and MODIS) and previous study; (b) enlarged map showing active faults interpreted in northern Thailand and surrounding areas. In both maps, individual fault zones are distinguished by color and numbered. The fault zones can be identified by numbers provided in Table 1.

ing the regional seismic hazard. Two kinds of seismic hazard analysis were investigated in this study: deterministic seismic hazard analysis (DSHA) (Costa *et al.*, 1992, 1993) and probabilistic seismic hazard analysis (PSHA) (Cornell, 1968). We also used two frequency-magnitude models to evaluate earthquake source potential in our PSHA.

The main objectives of this study were to reveal a worst case scenario for critical seismic hazards in the study area using the DSHA approach and to investigate the sensitivity of PSHA for a non-critical construction plan. We suggest that these complementary DSHA and PSHA approaches can provide a seismic hazard assessment that is more detailed and up-to-date than that currently available. We also expect that engineers will be able to use our results to facilitate the incorporation of seismic design maps into the International Building Code, with the ultimate aim being improved building design and construction.

## 2. Seismic Hazard Analysis

DSHA requires the determination of the expected maximum magnitude or maximum credible earthquake that may occur on individual faults. An empirical strong ground-motion attenuation model is employed to evaluate ground-shaking at given sites. The shortest source-to-site distance is then selected and the worst case scenarios for specific areas determined.

In contrast, the PSHA approach estimates the probability that a particular ground-shaking intensity measure  $A$  is equal to or exceeds the ground-shaking level  $A_0$  (Cornell,

1968):

$$\lambda(A \geq A_0) = \sum_{i=1}^{N_s} v_i \iint P[A(m, r) \geq A_0 | m, r] \cdot f_{M_i}(m) f_{R_i}(r) dm dr, \quad (1)$$

where  $\lambda(A \geq A_0)$  represents the frequency of exceedance of a given threshold value  $A_0$ ;  $f_{M_i}(m)$  is the probability density function that describes the probability of occurrence of each earthquake having a magnitude in a given range;  $f_{R_i}(r)$  is the probability density function for source-to-site distance;  $P[A(m, r) \geq A_0 | m, r]$  is the probability of exceedance of a threshold value  $A_0$ , under the condition that an event of magnitude  $m$  occurred at source-to-site distance  $r$ . The value of  $P[A(m, r) \geq A_0 | m, r]$  depends on the strong ground-motion attenuation model used. The coefficient  $v_i$  represents the activity rate, which implies the average rate of earthquake occurrence, for individual fault  $i$  from the total of considering fault ( $N_s$ ).

When a single fault  $i$  is considered to be a threat for the areas of interest, it is critical to select the appropriate frequency-magnitude model (i.e., probability density function) and activity rate. In this study, as mentioned above, we selected two frequency-magnitude models: the exponential magnitude distribution model and the characteristic earthquake model (Youngs and Coppersmith, 1985).

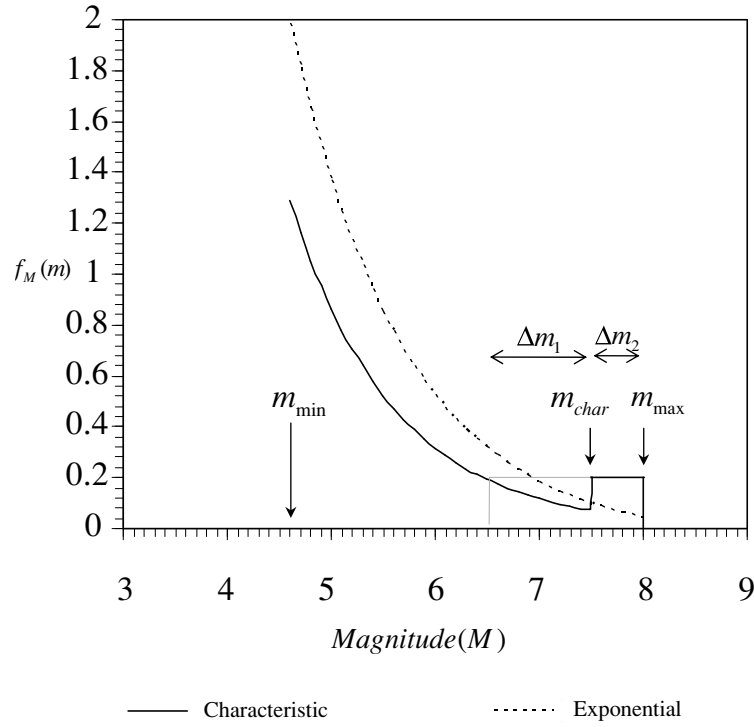


Fig. 2. Magnitude probability density function for the exponential magnitude distribution model (dashed line) and for the characteristic earthquake model (solid line) (Convertito *et al.*, 2006).

## 2.1 Model 1: Exponential magnitude distribution model

In general, the probabilities of earthquake occurrence on a given fault follow the Gutenberg-Richter (G-R) relationship (Gutenberg and Richter, 1954; Richter, 1958):

$$N(m) = 10^{a-bm} = e^{(\alpha-\beta m)}, \quad (2)$$

where  $N(m)$  is the number of events that are equal to or larger than a given magnitude  $m$ ,  $a$  and  $b$  are constants, and  $\beta = 2.303b$  and  $\alpha = 2.303a$ .

Youngs and Coppersmith (1985) proposed the exponential magnitude distribution approach to deal with maximum magnitude ( $m_{\max}$ ) and minimum magnitude ( $m_{\min}$ ) on individual earthquake sources. The lower threshold  $m_{\min}$  can be evaluated from earthquake catalog data. If  $m_{\max}$  is known or can be estimated, the cumulative distribution function for the G-R relationship, with upper and lower bounds, can be expressed as an exponential magnitude distribution model ( $f_{M\exp}(m)$ ) as follows (dashed line in Fig. 2):

$$f_{M\exp}(m) = \begin{cases} 0 & \text{for } m < m_{\min}, \\ \frac{\beta e^{-\beta(m-m_{\min})}}{1 - e^{-\beta(m_{\max}-m_{\min})}} & \text{for } m_{\min} \leq m \leq m_{\max}, \\ 0 & \text{for } m > m_{\max}. \end{cases} \quad (3)$$

Youngs and Coppersmith (1985) also determined an expression for the activity rate ( $v_{\exp}$ ) for the exponential magnitude distribution model:

$$v_{\exp} = \frac{\mu A_f S(c-b) [1 - e^{-\beta(m_{\max}-m_{\min})}]}{b M_0^{\max} e^{-\beta(m_{\max}-m_{\min})}}, \quad (4)$$

where  $\mu$  is the rigidity or shear modulus (usually taken to be  $\sim 3 \times 10^2$  newtons/m<sup>2</sup>),  $A_f$  is the rupture area (km<sup>2</sup>),  $S$  is the

slip rate (mm/year) for individual faults,  $M_0^{\max}$  is the seismic moment for  $m_{\max}$ , and  $c$  is a constant derived from the relationship between seismic moment ( $M_0$ ) and magnitude ( $m$ ) (Eq. (5)). The relationship between  $M_0$  and  $m$  has not previously been proposed for the Thailand region. In this study, therefore, we assume that the constants  $c = 1.5$  and  $d = 16.1$ , as proposed by Hanks and Kanamori (1979):

$$\log M_0 = cm + d. \quad (5)$$

## 2.2 Model 2: Characteristic earthquake model

This model is based on the hypothesis that individual faults tend to generate similar-sized or “characteristic” earthquakes and that these characteristic earthquakes occur on a fault not to the exclusion of all other magnitudes, but with a non-exponential frequency distribution (solid line in Fig. 2) (Youngs and Coppersmith, 1985; Convertito *et al.*, 2006). When the characteristic earthquake model is assumed, it is possible to formulate the corresponding ( $f_{M\text{char}}(m)$ ) as follows:

$$f_{M\text{char}}(m) = \begin{cases} 0 & \text{for } m < m_{\min}, \\ \frac{\beta e^{-\beta(m-m_{\min})}}{1 - e^{-\beta(m_{\max}-m_{\min})}} \frac{1}{1+c} & \text{for } m_{\min} \leq m \leq m_{\text{char}} = m_{\max} - \Delta m_2, \\ \frac{\beta e^{-\beta(m_{\max}-m_{\min}-\Delta m_1-\Delta m_2)}}{1 - e^{-\beta(m_{\max}-m_{\min}-\Delta m_2)}} \frac{1}{1+c} & \text{for } m_{\max} - \Delta m_2 = m_{\text{char}} \leq m \leq m_{\max}, \\ 0 & \text{for } m > m_{\max}. \end{cases} \quad (6)$$

Here, the constant  $c$  in Eq. (6) is given by:

$$c = \frac{\beta e^{-\beta(m_{\max}-m_{\min}-\Delta m_1-\Delta m_2)}}{1 - e^{-\beta(m_{\max}-m_{\min}-\Delta m_2)}} \Delta m_2.$$

Parameters  $\beta$ ,  $m$ ,  $m_{\min}$ , and  $m_{\max}$  are the same as in previous equations;  $\Delta m_1$  and  $\Delta m_2$  represent two intervals, below and above the magnitude level  $m_{\text{char}}$ , respectively, which is the characteristic earthquake magnitude (Fig. 2). Youngs and Coppersmith (1985) proposed values of 1.0 for  $\Delta m_1$  and 0.5 for  $\Delta m_2$ . Note the unique characteristic of  $f_{M_{\text{char}}}(m)$ , which refers to earthquakes with a magnitude in the range from  $m_{\text{char}}$  to  $m_{\max}$  (the “black plateau” part of the curve of Fig. 2). Youngs and Coppersmith (1985) also showed that the activity rate ( $v_{\text{char}}$ ) between  $m_{\text{char}}$  and  $m_{\max}$  is given by:

$$v_{\text{char}} = v_{\text{NC}} \frac{\beta \Delta m_2 e^{-\beta(m_{\max}-m_{\min}-\Delta m_1-\Delta m_2)}}{1 - e^{-\beta(m_{\max}-m_{\min}-\Delta m_2)}}, \quad (7)$$

where  $v_{\text{NC}}$  (Eq. (8)) represents the activity rate for the non-characteristic part ( $m_{\min} \leq m \leq m_{\text{char}}$ ) of  $f_{M_{\text{char}}}(m)$ :

$$v_{\text{NC}} = \frac{\mu A_f S [1 - e^{-\beta(m_{\max}-m_{\min}-\Delta m_2)}]}{K M_0^{\max} e^{-\beta(m_{\max}-m_{\min}-\Delta m_2)}}. \quad (8)$$

The constant  $K$  is given by

$$K = \frac{b 10^{-c \Delta m_2}}{c - b} \frac{b e^{\beta \Delta m_1} (1 - 10^{-c \Delta m_2})}{c}. \quad (9)$$

In summary, for PSHA, using either the exponential magnitude distribution model or the characteristic earthquake model, the data necessary to evaluate earthquake source potential are the maximum magnitude ( $m_{\max}$ ), minimum magnitude ( $m_{\min}$ ), slip rate ( $S$ ), earthquake rupture area ( $A_f$ ), and  $a$  and  $b$  values from the G-R relationship.

### 3. Materials and Methods

#### 3.1 Active fault data

The basic material underpinning the seismic hazard analysis of this study was an active fault map of the study area. We identified active faults in Thailand and neighboring areas from high-resolution remote sensing data. We also analyzed satellite images from IKONOS, LANDSAT, and MODIS, including a digital elevation model with 90-m resolution. The names and locations of individual fault zones are cited mostly from previous publications, but there are also new fault zones proposed in this study (Fig. 1; Table 1).

**3.1.1 Active faults outside Thailand** Identified active faults outside Thailand are distributed mainly in central Myanmar, on Sumatra Island, in the Laos-southern China border region, and in northern Vietnam (Fig. 1(a)). The major active fault zone in Myanmar is the strike-slip Sagiang fault zone (Bertrand and Rangin, 2003) (no. 38 in Fig. 1(a)). This fault zone traverses the central part of Myanmar from north to south. Although a morphotectonic representation of this feature cannot be identified in the Andaman Sea, present-day earthquake records show that the Sagiang fault extends southward into the Andaman Sea and joins with the clearly defined fault zones of inland Sumatra (Petersen *et al.*, 2004). We therefore defined the Sumatra

fault zone as the southern extension of the Sagiang fault (no. 38 in Fig. 1(a)). In the Laos-southern China border region, there are a large number of fault and shear zones caused by the collision of the Indian and Eurasian tectonic plates (Polachan *et al.*, 1991). These include the Chong Shan shear zone (Akciz *et al.*, 2008), the Dein Bein Fu fault zone (Zuchiewicz *et al.*, 2004), the Gaoligong Shan shear zone (Akciz *et al.*, 2008), the Hsenwi-Nanting fault zone (Lacassin *et al.*, 1998), and the Linchang fault zone (Lacassin *et al.*, 1998) (nos. 3, 4, 6, 7, and 15 in Fig. 1(a) and Table 1). Present-day earthquake records show that these complex zones have generated seismic activity continuously since the start of record keeping. In northern Vietnam, the longest fault zone is the Red River fault zone (Duong and Feigl, 1999) (no. 37 in Fig. 1(a)). A number of other obvious fault zones have been reported in this region, such as the Cao Bang-Tien Yen (Cuong *et al.*, 2006), Dong Trieu (Charusiri *et al.*, 2002), Song Ca (Takemoto *et al.*, 2005), Song Chay (Cuong and Zuchiewicz, 2001), and Song Da and Song Ma (Phoung, 1991) fault zones (nos. 1, 5, 40, 41, 42, and 43 in Fig. 1(a) and Table 1). All of these fault zones have a NW-SE orientation. Present-day earthquake records from this area show that earthquakes are commonly associated with these fault zones.

**3.1.2 Active faults in Thailand** There are a large number of active fault zones in northern Thailand, including the Lampang-Thoen (Charusiri *et al.*, 2004), Mae Chan (Fenton *et al.*, 2003), Mae Tha (Rhodes *et al.*, 2004), and Phrae (Fenton *et al.*, 2003) fault zones (nos. 12, 19, 22, and 33 in Fig. 1(b) and Table 1). These fault zones are associated with Cenozoic intermontane grabens and half grabens between intra-plate basins in northern Thailand and consist of north- to northwest-striking normal to trans-extensional faults and northeast-striking left-lateral strike-slip faults (Fenton *et al.*, 2003).

There are four major fault zones in western Thailand: the Mae Hong Sorn-Tak (Charusiri *et al.*, 2004), Sri Sawat (Songmuang *et al.*, 2007), Three Pagoda (Fenton *et al.*, 2003) fault zones, and the newly defined Moei-Tongyi fault zone (no. 20 in Fig. 1(b) and nos. 44, 49, and 26 in Fig. 1(a) and Table 1). We grouped the Moei-Mae Ping fault (Saithong *et al.*, 2005) and the Tongyi fault (Nutalaya *et al.*, 1985) into the Moei-Tongyi fault zone on the basis of morphotectonic evidence from satellite imagery.

The Ongkalak fault zone (no. 29 in Fig. 1(a)) was identified in central Thailand by Charusiri (2005), who considered it to be a branch of the Moei-Tongyi fault. However, it was previously named the Mae Ping fault by Polachan *et al.* (1991). Although there is no evidence of present-day seismicity in the Ongkalak fault zone, a paleoseismological study by Charusiri (2005) indicated a slip rate of 0.17 mm/yr and suggested that the fault zone is capable of generating an earthquake up to  $M_w 7$ . We consider the Ongkalak fault zone to be one of the major earthquake sources in central Thailand.

There are two major active faults in southern Thailand: the Klong Marui fault zone in the north and the Ranong fault zone in the south (Wong *et al.*, 2005) (nos. 10 and 36 in Fig. 1(a) and Table 1). Both fault zones strike NE-SW.

The northeastern highlands of Thailand are far from

Table 1. Summary of the earthquake potential parameters of the active fault zones used for seismic hazard analysis in Thailand and adjacent areas.

Fault no.	Fault zone	Active fault data					Seismicity investigation			Source
		Fault type <sup>a</sup>	SRL (km)	$S$ (mm/yr)	$m_{\max}$	$A_f$ (km <sup>2</sup> )	$m_{\min}$	$a$ value	$b$ value	
1	Cao Bang-Tien Yen	S	287	—	7.9	5,000	4.0	1.50	0.34	Cuong <i>et al.</i> (2006)
2	Chiang Rai	S	28	—	6.8	499	4.0	2.25	0.42	This study
3	Chong Shan shear zone	S	298	5.00	8.0	6,166	4.0	7.85	1.34	Akciz <i>et al.</i> (2008)
4	Dein Bein Fu	S	130	2.00	7.5	2,163	4.0	2.68	0.37	Zuchiewicz <i>et al.</i> (2004)
5	Dong Trieu	S, N	187	—	7.7	3,289	4.0	2.71	0.90	Charusiri <i>et al.</i> (2002)
6	Gaoligong Shan shear zone	S	407	5.00	8.1	7,603	4.0	9.67	1.62	Akciz <i>et al.</i> (2008)
7	Hsenwi-Nanting	S	359	1.00	8.0	6,166	4.0	25.80	4.83	Lacassin <i>et al.</i> (1998)
8	Jinghong	S	53	—	7.1	935	4.0	2.33	0.40	Lacassin <i>et al.</i> (1998)
9	Kawthuang	—	36	—	6.9	615	4.0	1.68	0.25	This study
10	Klong Marui	S	29	0.10	6.8	499	4.0	1.68	0.25	Wong <i>et al.</i> (2005)
11	Kungyaungale	S	25	4.00	6.7	405	4.0	1.68	0.25	Wong <i>et al.</i> (2005)
12	Lampang-Thoen	S, N	28	0.83	6.8	499	4.0	2.72	0.55	Charusiri <i>et al.</i> (2004)
13	Lashio	S	50	1.00	7.0	759	4.0	3.15	0.40	Lacassin <i>et al.</i> (1998)
14	Libir	—	170	—	7.7	3,289	4.0	3.44	0.60	Metcalf (2000)
15	Linchang	S	107	—	7.4	1,754	4.0	2.33	0.29	Lacassin <i>et al.</i> (1998)
16	Loei-Petchabun Suture	S	59	—	7.1	935	4.0	3.01	0.62	Lepvrier <i>et al.</i> (2004)
17	Longling-Ruili	S	70	5.00	7.2	1,153	4.0	6.42	1.01	Bai and Meju (2003)
18	Mae Chaem	—	21	—	6.6	328	4.0	1.89	0.32	This study
19	Mae Chan	S	99	3.00	7.4	1,754	4.0	2.64	0.37	Fenton <i>et al.</i> (2003)
20	Mae Hong Sorn-Tak	S	37	—	6.9	615	4.0	2.65	0.38	Charusiri <i>et al.</i> (2004)
21	Mae Ing	S	38	—	6.9	615	4.0	2.56	0.38	Fenton <i>et al.</i> (2003)
22	Mae Tha	S	47	0.80	7.0	759	4.0	2.36	0.38	Rhodes <i>et al.</i> (2004)
23	Mae Yom	S	22	0.80	6.6	328	4.0	1.92	0.60	RID (2006)
24	Menglian	S	117	0.50	7.5	2,163	4.0	2.13	0.28	Lacassin <i>et al.</i> (1998)
25	Mengxing	S	75	4.80	7.3	1,422	4.0	2.95	0.40	Lacassin <i>et al.</i> (1998)
26	Moei-Tongyi	S	259	0.73	7.9	5,000	4.0	3.46	0.54	This study
27	Nam Ma	S	177	2.40	7.7	3,289	4.0	3.18	0.58	Morley (2007)
28	Nam Peng	S	51	—	7.1	935	4.0	3.08	0.59	Charusiri <i>et al.</i> (1999)
29	Ongkalak	S, N	47	0.17	7.0	759	4.0	2.52	0.40	Charusiri (2005)
30	Pa Pun	S	143	—	7.6	2,667	4.0	2.58	0.37	Nutalaya <i>et al.</i> (1985)
31	Pan Luang	S	219	—	7.8	4,055	4.0	2.98	0.51	Nutalaya <i>et al.</i> (1985)
32	Pha Yao	S, N	20	0.10	6.6	328	4.0	2.95	0.40	Fenton <i>et al.</i> (2003)
33	Phrae	S	28	0.10	6.8	499	4.0	2.68	0.53	Fenton <i>et al.</i> (2003)
34	Pua	N	29	0.60	6.8	499	4.0	2.44	0.55	Fenton <i>et al.</i> (2003)
35	Qiaohou	—	145	—	7.6	2,667	4.0	2.35	0.25	Lacassin <i>et al.</i> (1998)
36	Ranong	S	46	1.00	7.0	759	4.0	1.68	0.25	Wong <i>et al.</i> (2005)
37	Red River	S	812	4.00	8.5	17,579	4.0	17.60	3.16	Duong and Feigl (1999)
38	Sagiang-Sumatra	S	958	23.00	8.5	17,579	4.0	6.92	0.86	Bertrand and Rangin (2003)
39	Shan	S	66	—	7.2	1,153	4.0	2.93	0.39	This study
40	Song Ca	S	225	—	7.8	4,055	4.0	2.58	0.48	Takemoto <i>et al.</i> (2005)
41	Song Chay	S, N	55	2.00	7.1	935	4.0	3.05	0.58	Cuong and Zuchiewicz (2001)
42	Song Da	S	46	—	7.0	759	4.0	2.73	0.45	Phoung (1991)
43	Song Ma	S	72	—	7.2	1,153	4.0	6.52	1.06	Phoung (1991)
44	Sri Sawat	S	43	2.00	7.0	759	4.0	2.50	0.40	Songmuang <i>et al.</i> (2007)
45	Andaman subduction	R	3,388	47.00	9.2	76,208	4.0	6.08	0.69	Paul <i>et al.</i> (2001)
46	Tavoy	S	32	—	6.8	499	4.0	2.80	0.79	Wong <i>et al.</i> (2005)
47	Tenasserim	S	50	4.00	7.0	759	4.0	1.68	0.25	Wong <i>et al.</i> (2005)
48	Tha Khaek	S	250	—	7.9	5,000	4.0	3.15	0.67	DMR (2006)
49	Three Pagoda	S	141	2.00	7.6	2,667	4.0	2.62	0.51	Fenton <i>et al.</i> (2003)
50	Uttaladith	S	27	0.10	6.7	405	4.0	1.63	0.46	Fenton <i>et al.</i> (2003)
51	Wan Na-awn	—	69	—	7.2	1,153	4.0	2.28	0.35	This study
52	Wanding	S	199	1.90	7.7	3,289	4.0	5.34	0.93	Morley (2007)
53	Wang Nua	—	31	—	6.8	499	4.0	2.27	0.40	This study
54	Xianshuihe	S	505	15.00	8.2	9,376	4.0	6.74	1.05	Eleftheria <i>et al.</i> (2004)
55	Hutgyi	S, R	5	0.03	5.9	76	4.0	1.67	0.34	EGAT (2006)

SRL is surface rupture length (km),  $m_{\max}$  is maximum possible earthquake magnitude calculated from empirical relationship between SRL and  $M_w$  (Wells and Coppersmith, 1994),  $A_f$  is rupture area (km<sup>2</sup>) calculated from the empirical relationship between  $A_f$  (Wells and Coppersmith, 1994),  $S$  is slip rate (mm/yr),  $m_{\min}$  is the minimum magnitude. <sup>a</sup>Fault type: S = strike-slip fault, N = normal fault, R = reverse fault.

known earthquake sources. The closest candidate is the Tha Khaek fault zone (DMR, 2006) (no. 48 in Fig. 1(a)) near the Thailand-Laos border. This fault zone is clearly indicated by the satellite image investigations, and one earthquake was recorded in 1988 and in 1997 with a local magnitude ( $M_L$ ) of 4.1 and 4.2, respectively. We therefore regard this fault zone to be one of the earthquake sources to be considered in this study.

**3.1.3 Maximum magnitudes and slip rates** After identifying 55 candidate active fault zones, we evaluated the earthquake potential of each zone by using both active fault data and seismicity data. To determine the possible  $m_{\max}$ , we used the relationship between  $M_w$  and fault rupture length at the surface (SRL), as proposed by Wells and Coppersmith (1994) (Eq. (10)). The SRL used for the  $M_w$  calculation is taken from the length of the longest fault segment in each fault zone. We then determined the rupture area  $A_f$  by using the empirical relationship between the obtained  $M_w$  from Eq. (10) and  $A_f$  (Wells and Coppersmith, 1994) of Eq. (11):

$$M_w = 5.08 + 1.16 \log(\text{SRL}), \quad (10)$$

$$\log(A_f) = -3.49 + 0.91 M_w, \quad (11)$$

where  $M_w$  is moment magnitude, SRL is surface rupture length of the fault (km), and  $A_f$  is the rupture area of the fault (km<sup>2</sup>).

For many of the faults within the study area, there have been few studies of slip rate ( $S$ ). However, we conducted a comprehensive literature search for information about slip rates, which are summarized in Table 1.

### 3.2 Earthquake catalog data

Although earthquake catalogs cover a much shorter time period than paleoseismological data, the earthquake records they provide are indispensable for seismic hazard analyses. In this study, we obtained several parameters necessary to determine earthquake potential from earthquake catalog records. The methodology we used to evaluate the seismicity data (earthquake catalogs) in each fault zone is based on the method proposed by Caceres and Kulhanek (2000) as follows:

- First, we collected earthquake records from various earthquake catalogs, such as the Incorporated Research Institutions for Seismology (IRIS), the global CMT catalogue, and the Thai Meteorological Department. We then constructed a composite earthquake catalog and eliminated overlapping earthquake events.
- We converted the various earthquake magnitude scales (i.e., body-wave magnitude ( $m_b$ ), surface-wave magnitude ( $M_s$ ), local magnitude ( $M_L$ ), and  $M_w$ ) in the composite earthquake catalog to moment magnitude ( $M_w$ ), which represents the physical properties of the earthquake source and avoids the “saturation phenomenon” at large seismic moments (e.g., Howell, 1981; Ottemoller and Havskov, 2003). The global CMT catalogue provides  $m_b$ ,  $M_s$ , and  $M_w$  magnitudes for individual earthquake events; we used these data from our study area to calibrate the relationship of  $M_w$  to both  $m_b$  and  $M_s$ . The relationships of  $M_w$  to  $m_b$  and  $M_s$  are formulated in Eqs. (12) and (13). For  $M_L$ , we

used the empirical relationship between  $M_L$  and  $m_b$  of Palasri (2006) (Eq. (14)) and then converted  $m_b$  to  $M_w$  using our Eq. (12).

$$M_w = 0.0167 m_b^2 + 0.8438 m_b + 0.9071; m_b \leq 6.8 \quad (12)$$

$$M_w = 0.028 M_s^2 + 0.3364 M_s + 3.2574; M_s \leq 7.6 \quad (13)$$

$$m_b = 1.64 + 0.63 M_L; M_L \leq 6.8 \quad (14)$$

- For conventional seismic hazard analysis, independent earthquake (main shock) events must be considered (Cornell, 1968). To satisfy this requirement, earthquakes in the study area were de-clustered to remove foreshocks and aftershocks by using the method of Gardner and Knopoff (1974).
- Thereafter, for each fault zone, the independent earthquakes within a 60-km-wide corridor straddling the fault zone were identified as representatives of the earthquake activity in that fault zone. The cumulative numbers of earthquakes within individual fault zones were plotted against moment magnitude to obtain G-R relationships. For this, we used ZMAP software (Wiemer, 2001) to estimate the optimal  $a$  and  $b$  values that best yielded the relationship between observed  $N(m)$  and  $m$  (Eq. (2)) for each fault zone. For all fault zones in this study, the  $m_{\min}$  is taken as 4.0. Below this lower threshold magnitude (i.e.,  $m_{\min}$ ), it is assumed that there is not any significant earthquake hazard on engineering structures (Kramer, 1996).

All fundamental earthquake source parameters (i.e.,  $m_{\max}$ ,  $m_{\min}$ ,  $A_f$ ,  $S$ , and  $a$  and  $b$  values) of the 55 earthquake sources are summarized in Table 1.

## 4. Strong Ground-Motion Attenuation Models

When earthquake potential parameters for individual fault zones have been determined, the next step for seismic hazard analysis is to select an appropriate strong ground-motion attenuation model. The characteristics of strong ground-motion attenuation are area-dependent and influenced by the local tectonic setting (e.g., subduction zone or inland continental region). We separated the 55 active fault zones into two seismotectonic provinces on the basis of tectonic setting: the subduction zone earthquake province for the Andaman subduction zone, and the shallow crustal earthquake province for the other 54 fault zones.

For the Andaman subduction zone, Petersen *et al.* (2004) compared previously used strong ground-motion attenuation models with the strong ground-motion data recorded by the IRIS network and suggested that the Andaman subduction zone shows the attenuation behavior of ground shaking consistent with that of Youngs *et al.* (1997) (Eq. (15)), but only if the source-to-site distance ( $R$ ) is less than 200 km.

$$\begin{aligned} \ln y_{\text{Youngs}}(M, R) = & C_1^* + C_2 M + C_3^* \ln \left[ R + e^{C_4^* - \frac{C_2}{C_3} M} \right] \\ & + C_5 Z_{SS} + C_8 Z_t + C_9 H \\ \text{with } C_1^* = & C_1 + C_3 C_4 - C_3^* C_4^* \quad (15) \\ C_3^* = & C_3 + C_6 Z_{SS} \\ C_4^* = & C_4 + C_7 Z_{SS}, \end{aligned}$$

where  $y$  is peak horizontal ground acceleration (cm/s<sup>2</sup>),

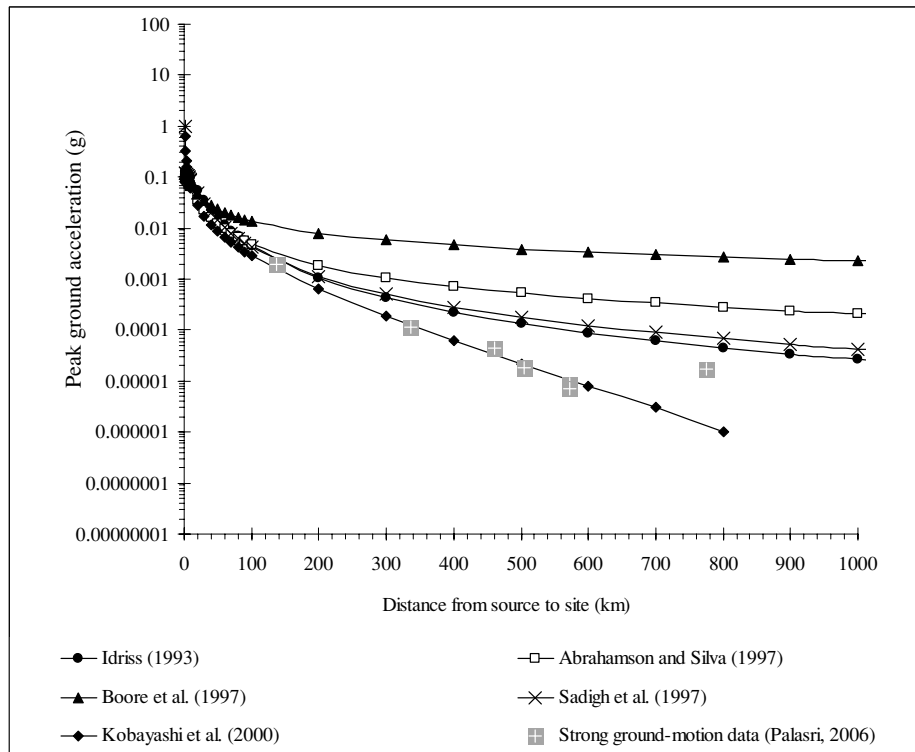


Fig. 3. Comparison of published strong ground-motion attenuation models with strong ground-motion data recorded in Thailand.

$M$  is moment magnitude ( $M_w$ ),  $R$  is source-to-site distance (km),  $C_1 = 0.2418$ ,  $C_2 = 1.414$ ,  $C_3 = -2.552$ ,  $C_4 = \ln(1.7818)$ ,  $C_8 = 0.3846$ , and  $C_9 = 0.00607$ .  $Z_{SS}$  is zero for a rock site and one for a soil site, and  $Z_t$  is zero for plate-interface earthquakes (low-angle, thrust-faulting earthquakes at plate interfaces), and one for intraslab earthquakes (high-angle, predominantly normal-faulting earthquakes within subducting plates).  $H$  is focal depth. The other coefficients in Eq. (15) are not required for a rock site. The standard deviation of  $\ln y(\sigma)$  for probability of the exceedance calculation is estimated as follows:  $\sigma = 1.45 - 0.1M$ .

If the source-to-site distance is  $\geq 200$  km, the attenuation behavior of Andaman subduction-zone earthquakes is expressed by the following equation (Eq. (16); Petersen *et al.*, 2004):

$$\ln y_{\text{Petersen}}(M, R) = \ln y_{\text{Youngs}}(M, R) + [-0.0038 * (R - 200)]. \quad (16)$$

For the shallow crustal earthquake fault zones, two strong ground-motion attenuation models have been suggested by previous investigations. Warnitchai and Lisantono (1996) applied the attenuation model of Esteva and Villaverde (1973) to seismic hazard analysis in Thailand. However, Palasri (2006) suggested that the attenuation model of Sadigh *et al.* (1997) is more suitable for Thailand and adjacent areas after comparing it with strong ground-motion data collected by the Thai Meteorological Department.

We compared several recently proposed attenuation models with observed strong ground-motion data from Thailand that were analyzed by Palasri (2006) (Fig. 3). This comparison suggests that an equation proposed by Kobayashi *et al.* (2000) for the Japan region (Eq. (17)) is the best fit for

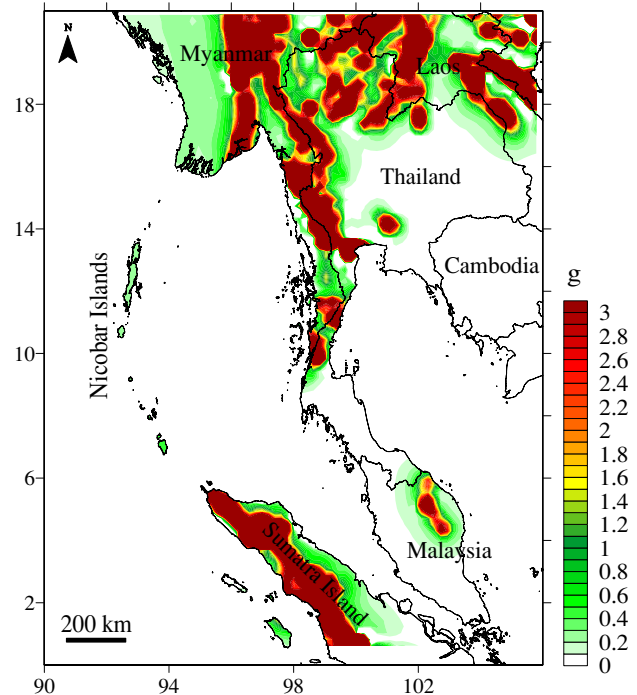


Fig. 4. Deterministic seismic hazard map of Thailand and adjacent areas using active fault data.

these data. We consider Eq. (17) to be suitable to represent the attenuation behavior of shallow crustal earthquakes in the study area.

$$\log y(M, R) = aM - bR - \log(R + c10^{dM}) + eh + S_k, \quad (17)$$

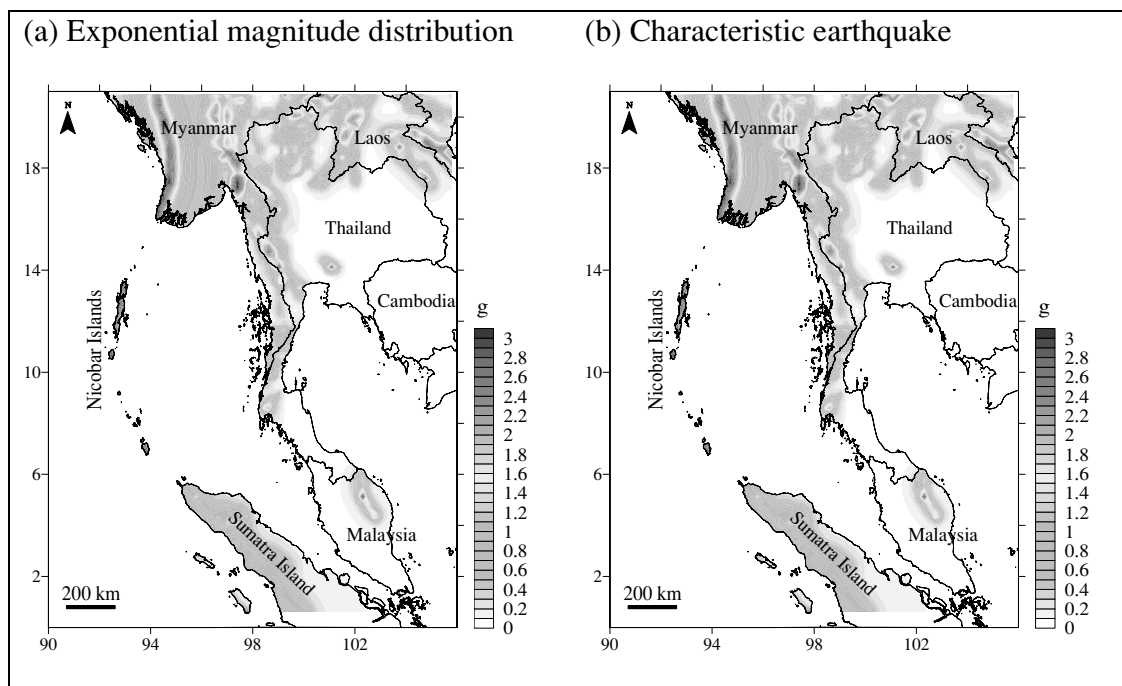


Fig. 5. Probabilistic seismic hazard maps of Thailand and adjacent areas showing 2% probability of exceedance in 50-year time period. (a) Exponential magnitude distribution model and (b) characteristic earthquake model.

where for any rock site,  $y$  is the peak ground acceleration ( $\text{cm/s}^2$ ),  $M$  is the moment magnitude ( $M_w$ ),  $R$  is the source-to-site distance (km),  $a = 0.578$ ,  $b = 0.00355$ ,  $c = 0.00661$ ,  $d = 0.00661$ ,  $e = 0.00661$ ,  $h = 10$ , and  $S_k = -0.21$ . The standard deviation of  $\ln y(\sigma)$  for probability of exceedance calculation is 0.213.

## 5. Seismic Hazard Analysis Results

### 5.1 DSHA

DSHA (Fig. 4), which does not account for the activity rate of earthquake occurrence, reveals an extremely high hazard level along the active fault zones. The peak ground acceleration (PGA) calculated by DSHA for the maximum credible earthquake ranges from 0 g in areas far from active faults to 3 g alongside the active faults. The earthquake-prone areas are in central Myanmar, Sumatra, Laos, southern China, northern Vietnam, and northern and western Thailand. In central Thailand, there is a high hazard level in the area close to the Ongkalak fault zone. There is a seismic hazard associated with the Ranong and Klong Marui fault zones in southern Thailand. For northeastern Thailand, although there has recently been a dramatic decrease in reports of earthquake ground shaking, the calculated seismic hazard reveals that the far north, close to the Tha Khaek Fault in Laos, may be subject to damage by seismic activity. In the Nicobar Islands and western Myanmar, close to the Andaman subduction zone, the DSHA map shows ground shaking of around 0.4–0.6 g.

### 5.2 PSHA

The PSHA initially produced two types of maps using different frequency-magnitude models: the exponential magnitude distribution model and the characteristic earthquake model (Fig. 5). Comparison of the exponential magnitude distribution model and the characteristic earthquake

model showed that they both provide similar seismic hazard levels. We attribute this similarity to the similar frequency-magnitude distributions obtained from active fault parameters. We calculated very similar magnitude probability density functions for the two models for two active fault zones and the Andaman subduction zone (Fig. 6). It is difficult to determine which of the two frequency-magnitude models is more appropriate for the study area because no evidence of characteristic earthquakes can be clearly identified in the instrumental earthquake records from 1963 to 2007 (Fig. 7). As a result, we determined the sensitivity of the PSHA results to the weights assigned to the logic-tree branches for both given frequency-magnitude models: the exponential magnitude distribution and characteristic earthquake models. Both of these are weighted in 0.5 probability of occurrence. PSHA maps were produced for bedrock conditions for a 2% and 10% probability of exceedance in 10-, 50-, and 100-year time periods (Fig. 8). The spatial distribution of seismic hazard from PSHA is also roughly analogous to that obtained by DSHA, but the maximum hazard level is lower in PSHA than in DSHA.

Taking a 10% probability of exceedance in a 50-year time period (Fig. 8(d)), PGA values indicate a high seismic hazard (up to 2 g) in countries neighboring Thailand. The trend of PGA in Thailand shows a high hazard level of around 0.8 g in the north and west, and it decreases gradually toward the east and southeast. One outstandingly high hazard area is in the Ongkalak fault zone in central Thailand, which shows the maximum hazard level in Thailand, up to 2 g. There are two major fault zones in southern Thailand: the Ranong and Klong Marui fault zones. Judging from the surface rupture length of these fault zones, both of them can generate an earthquake with a maximum magnitude of around 6.8–7. However, the Ranong fault zone has a slip

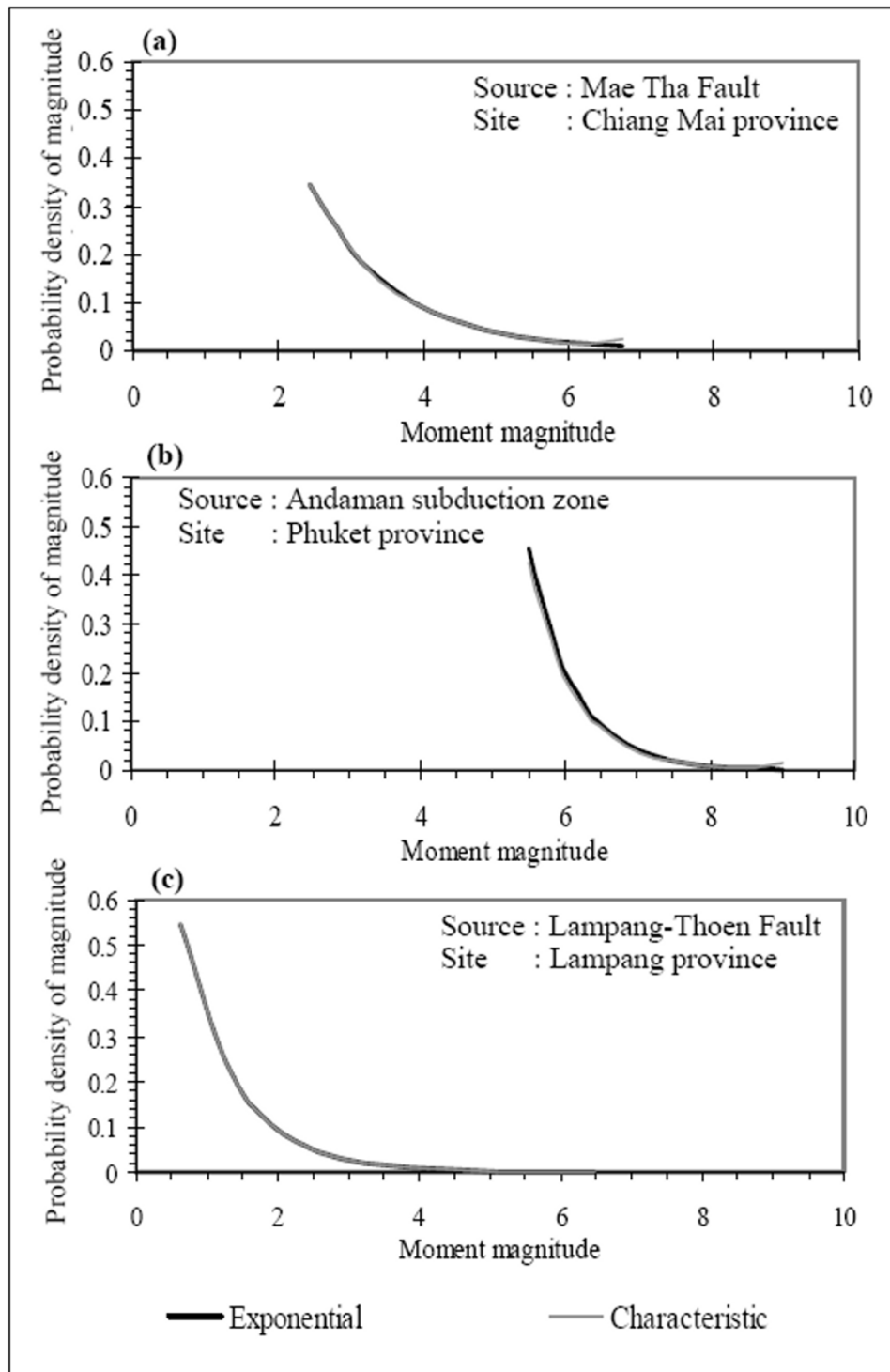


Fig. 6. Comparisons of magnitude probability density functions for (a) the Mae Tha fault, (b) the Andaman subduction zone, and (c) the Lampang-Thoen fault. Gray lines represent the results calculated from the characteristic earthquake model, and black lines represent the exponential magnitude distribution model.

rate of 1 mm/yr, whereas the slip rate of the Klong Marui fault zone is 0.1 mm/yr (Table 1). The Klong Marui fault zone, therefore, does not have any significant effect on seismic hazard in this area.

## 6. Discussion and Conclusions

We have used active fault parameters estimated from remote sensing data and previous studies, including the best-

fit strong ground-motion attenuation models, to evaluate the seismic hazard in Thailand and adjacent areas.

For DSHA, we assumed a worst case scenario for each active fault zone. The PGA values from DSHA were up to 2–3 g along many active fault zones; this result may be somewhat overestimated because of the conservatively determined  $m_{\max}$  from the limited amount of active fault data. Although most of the earthquakes during this period

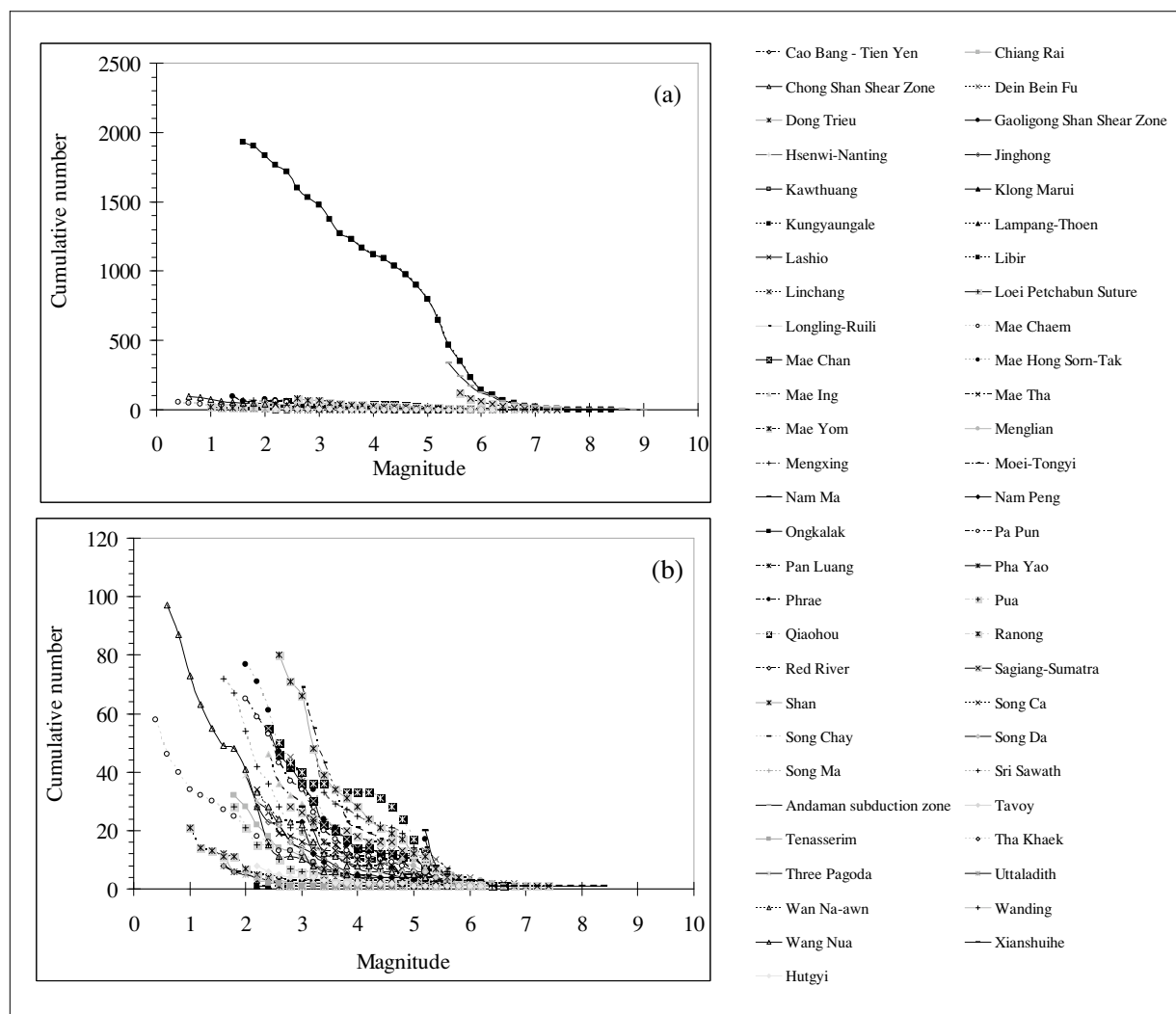


Fig. 7. Summary of the Gutenberg-Richter relationships for earthquake events within individual active fault zones identified in this study.

were less than  $M_w$  6, paleoseismological studies in some areas revealed that some earthquakes earlier than those recorded in the instrumental record time span were larger (e.g., Fenton *et al.*, 2003; Charusiri *et al.*, 2004; Rhodes *et al.*, 2004; RID, 2006). Paleoseismological studies have also clearly shown that the recurrence intervals of earthquakes produced by active faulting are several hundred to several thousand years; for example, 720 years for the Kao Ka Reang fault of the Ongkalak fault zone (Charusiri, 2005), and 4,200 years for the Ton Ngoon fault of Lampang-Thoen fault zone (Charusiri *et al.*, 2004). We concluded, therefore, that Thailand and adjacent areas may be exposed to large earthquakes with strong ground shaking, as shown by our deterministic seismic hazard map (Fig. 4). However, the DSHA also showed the seismic hazard level to be lower than our expectations in some areas, such as the Nicobar Islands and western Myanmar. Although these areas are close to the Andaman subduction zone, the DSHA showed a possible ground shaking range of 0.4–0.6 g. We attribute this low seismic hazard to the strong ground-motion attenuation model we used for the subduction zone. The subduction zone attenuation model of Petersen *et al.* (2004) generated a lower seismic hazard level than the attenuation model of

Kobayashi *et al.* (2000) for shallow crustal (inland) earthquakes.

In our PSHA, both the exponential magnitude distribution model and the characteristic earthquake model were applied. The obtained probabilistic seismic hazard maps revealed quite similar hazard levels. No obvious evidence indicated which frequency-magnitude models are the more appropriate for this study. Therefore, probabilistic seismic hazard calculation using the logic tree weighting of both frequency-magnitude models have been performed, as shown in Fig. 8. We believe that the map derived from our DSHA (Fig. 4), in conjunction with those from our PSHA (Fig. 8), will be useful for planning and locating future structures in Thailand and adjacent areas. According to the Krinitzsky (2003) suggestion, DSHA is useful for designing critical structures, such as the nuclear power plants. However, PSHA can be applied for preliminary evaluations or for risk analysis when these are unrelated to design decisions on a critical construction.

Finally, we emphasize that the extent to which geological information contributes to seismic hazard assessment in Thailand and adjacent areas and that such assessments depend on the quantity and quality of the data collected. To

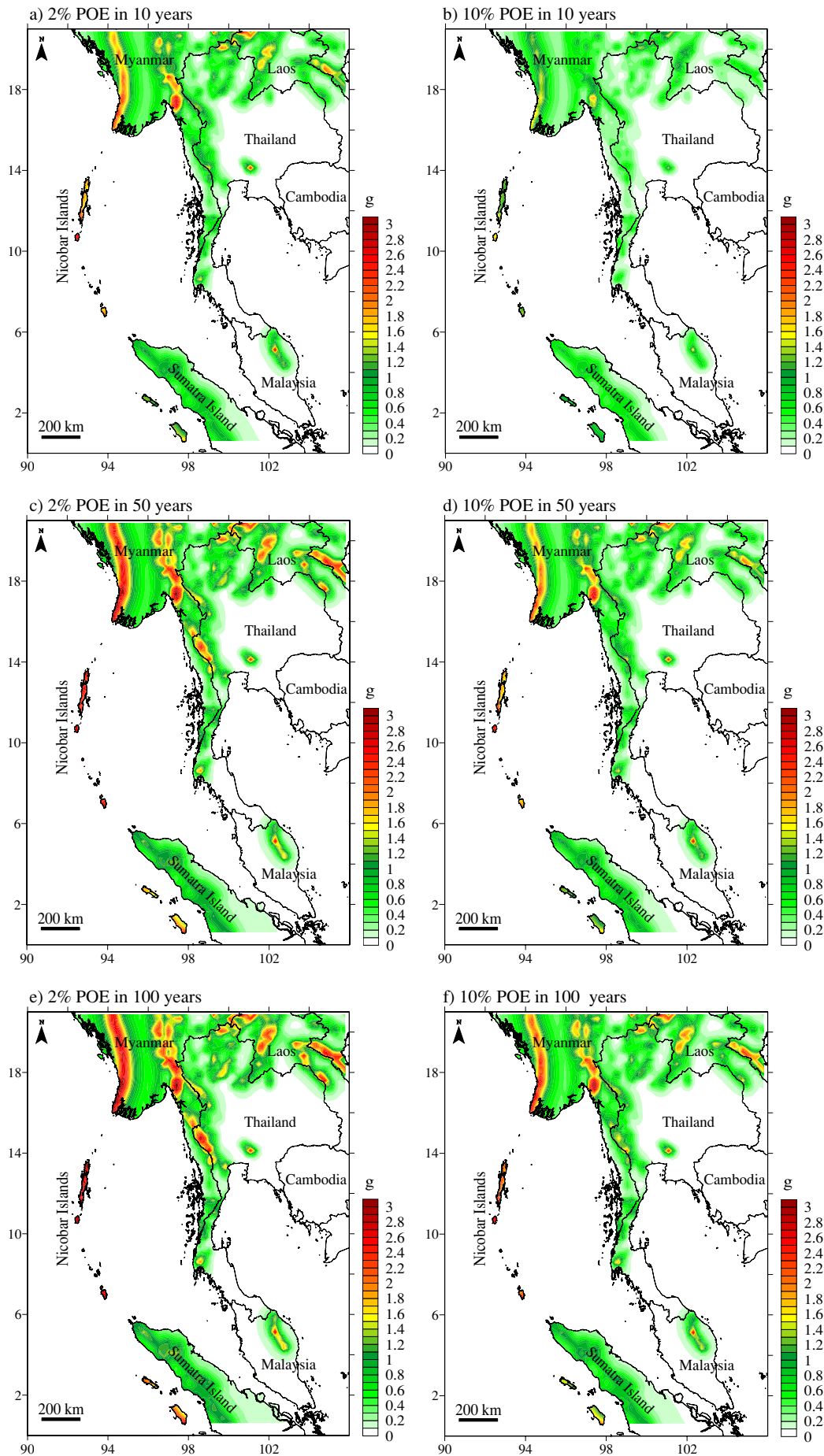


Fig. 8. Probabilistic seismic hazard maps of Thailand and adjacent areas. POE is probability of exceedance in specific time period (year).

further refine seismic hazard analysis in this region, more detailed active fault data are indispensable. To this end, more ground motion recording stations are needed to allow the construction of a strong ground-motion attenuation model specific to Thailand and adjacent areas.

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